

SSCE 2393 NUMERICAL METHODS

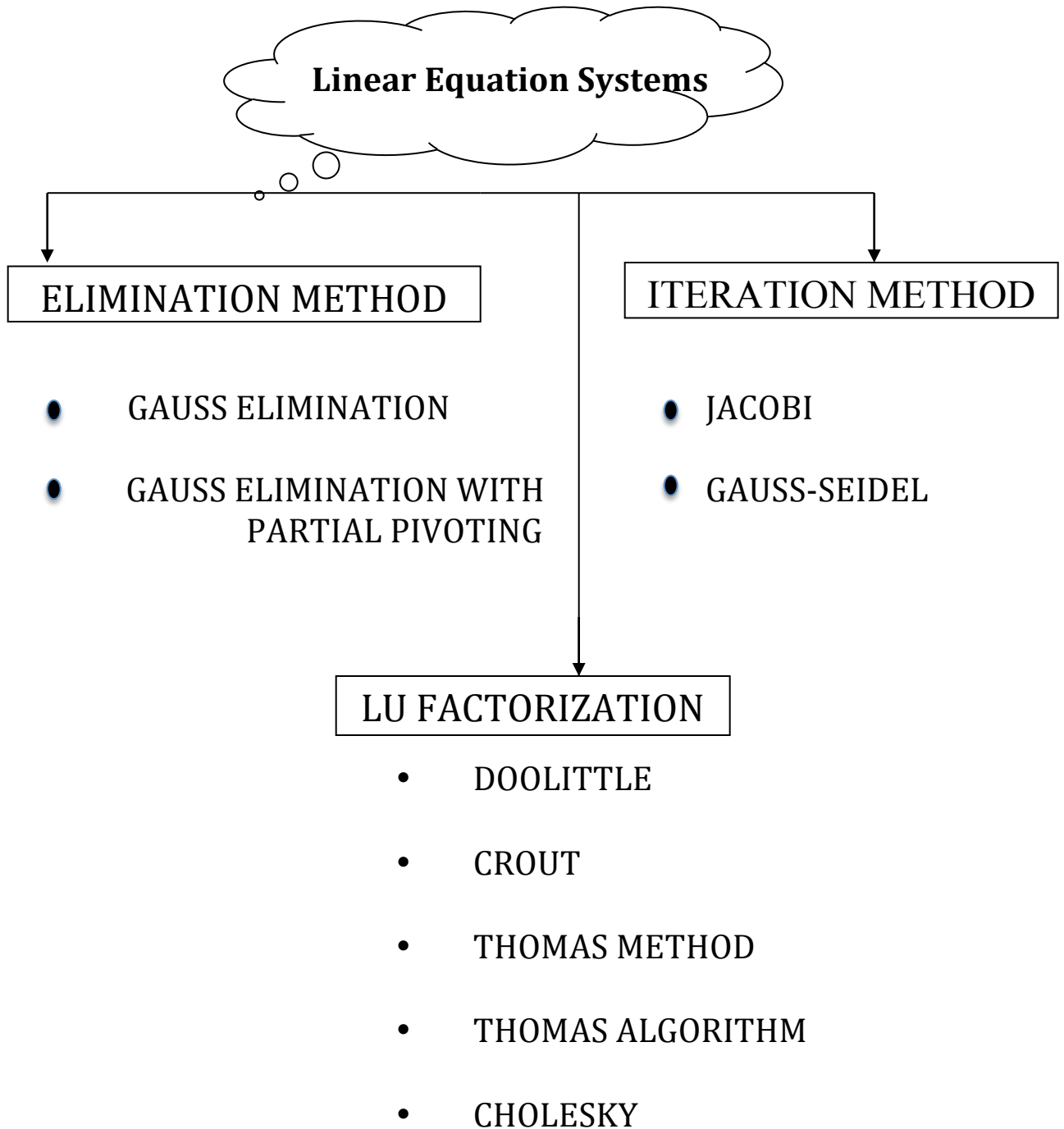
CHAPTER 2

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LINEAR EQUATION SYSTEMS

## Overview Chapter 2

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## 2.1 Elimination Method

- **Gauss Elimination**
- **Gauss elimination with partial pivoting**

### 2.1.1 Gauss Elimination

Given:

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 = b_1$$

$$a_{21}x_1 + a_{22}x_2 + a_{23}x_3 = b_2$$

$$a_{31}x_1 + a_{32}x_2 + a_{33}x_3 = b_3$$

Written in augmented matrix form as:

$$\left[ \begin{array}{ccc|c} a_{11} & a_{12} & a_{13} & b_1 \\ a_{21} & a_{22} & a_{23} & b_2 \\ a_{31} & a_{32} & a_{33} & b_3 \end{array} \right] \xrightarrow{\text{Elementary row operations}} \left[ \begin{array}{ccc|c} u_{11} & u_{12} & u_{13} & f_1 \\ 0 & u_{22} & u_{23} & f_2 \\ 0 & 0 & u_{33} & f_3 \end{array} \right]$$

$$\mathbf{Ax} = \mathbf{b}$$

$$\mathbf{Ux} = \mathbf{f}$$

↓ Elementary row operations

$$\left( \begin{array}{ccc} u_{11} & u_{12} & u_{13} \\ 0 & u_{22} & u_{23} \\ 0 & 0 & u_{33} \end{array} \right) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \\ f_3 \end{pmatrix}$$

← Backward subst.

$$\begin{aligned} x_3 &= f_3 / u_{33} \\ x_2 &= (f_2 - u_{23}x_3) / u_{22} \\ x_1 &= (f_1 - u_{12}x_2 - u_{13}x_3) / u_{11} \end{aligned}$$

Example 1:

Solve the following linear system using Gauss elimination method.

$$2.51x_1 + 1.48x_2 + 4.53x_3 = 5.56$$

$$1.48x_1 + 0.93x_2 - 1.30x_3 = -0.75$$

$$2.68x_1 + 3.04x_2 - 1.48x_3 = -1.84$$

**Solution**

$$\left[ \begin{array}{ccc|c} 2.51 & 1.48 & 4.53 & 5.56 \\ 1.48 & 0.93 & -1.30 & -0.75 \\ 2.68 & 3.04 & -1.48 & -1.84 \end{array} \right] \xrightarrow{B_2 \rightarrow -0.59B_1 + B_2} \left[ \begin{array}{ccc|c} 2.51 & 1.48 & 4.53 & 5.56 \\ 0 & 0.06 & -3.97 & -4.03 \\ 2.68 & 3.04 & -1.48 & -1.84 \end{array} \right]$$

multiplier,  $m_{21} = a_{21}/a_{11} = 0.59$

multiplier,  $m_{31} = a_{31}/a_{11} = 1.07$

$$\xrightarrow{B_3 \rightarrow -1.07B_1 + B_3} \left[ \begin{array}{ccc|c} 2.51 & 1.48 & 4.53 & 5.56 \\ 0 & 0.06 & -3.97 & -4.03 \\ 0 & 1.46 & -6.33 & -7.79 \end{array} \right] \xrightarrow{B_3 \rightarrow -24.33B_2 + B_3}$$

multiplier,  $m_{32} = a_{32}/a_{22} = 24.33$

$$\rightarrow \left[ \begin{array}{ccc|c} 2.51 & 1.48 & 4.53 & 5.56 \\ 0 & 0.06 & -3.97 & -4.03 \\ 0 & 0 & 90.26 & 90.26 \end{array} \right]$$

$\therefore$  Using backward substitution, we get:

$$x_3 = 1$$

$$x_2 = -1$$

$$x_1 = 1$$

Exercise:

Solve the following linear systems using Gauss elimination method:

1. Use 4 decimal places.

$$\begin{bmatrix} 5 & -1 & 1 \\ 2 & 4 & 0 \\ 1 & 1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 12 \\ -1 \end{bmatrix}$$

2. Use 3 decimal places.

$$\begin{aligned} 8x_1 + 2x_2 - x_3 + 2x_4 &= -2 \\ x_1 - 8x_2 + x_3 - 2x_4 &= 4 \\ 2x_1 - x_2 + 7x_3 - x_4 &= -1 \\ -2x_1 + x_2 - 3x_3 - 8x_4 &= 3 \end{aligned}$$

*Ans:*  $x_3 = -1.0555$ ,  $x_2 = 1.7222$ ,  $x_1 = 2.5555$

$x_4 = -0.325$ ,  $x_3 = -0.231$ ,  $x_2 = -0.458$ ,  $x_1 = -0.083$

## 2.1.2 Gauss Elimination with Partial Pivoting

why????

- to solve problem that involve division by zero (in case  $a_{11} = 0$  or  $a_{22} = 0$ )
- reduce the round-off errors.

The algorithm follows the Gauss elimination method **except:**

- Interchange rows when needed at the  $k$ -th step so that the absolute value of pivot element  $a_{kk}$  is the largest element compare to the other elements underneath the pivot.

Then, do the elimination process.

Example 2:

Use Gauss elimination method with partial pivoting to solve:

$$\begin{bmatrix} 0 & 0 & 3 & 4 \\ 2 & 9 & 1 & 0 \\ 0 & 1 & 9 & 4 \\ 5 & 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 8 \\ 6 \\ 8 \\ 9 \end{bmatrix}$$

## Solution

$$\begin{pmatrix} 0 & 0 & 3 & 4 & | & 8 \\ 2 & 9 & 1 & 0 & | & 6 \\ 0 & 1 & 9 & 4 & | & 8 \\ 5 & 1 & 0 & 0 & | & 9 \end{pmatrix} B_1 \leftrightarrow B_4 \xrightarrow{m_{21} = \frac{2}{5}} \begin{pmatrix} 5 & 1 & 0 & 0 & | & 9 \\ 2 & 9 & 1 & 0 & | & 6 \\ 0 & 1 & 9 & 4 & | & 8 \\ 0 & 0 & 3 & 4 & | & 8 \end{pmatrix} \xrightarrow{B_2 := -m_{21}B_1 + B_2}$$
$$\begin{pmatrix} 5 & 1 & 0 & 0 & | & 9 \\ 0 & 8.6 & 1 & 0 & | & 2.4 \\ 0 & 1 & 9 & 4 & | & 8 \\ 0 & 0 & 3 & 4 & | & 8 \end{pmatrix} \xrightarrow{m_{32} = \frac{1}{8.6}} \begin{pmatrix} 5 & 1 & 0 & 0 & | & 9 \\ 0 & 8.6 & 1 & 0 & | & 2.4 \\ 0 & 0 & 8.8837 & 4 & | & 7.7209 \\ 0 & 0 & 3 & 4 & | & 8 \end{pmatrix} \xrightarrow{B_3 := -m_{32}B_2 + B_3}$$
$$\xrightarrow{m_{43} = \frac{3}{8.8837}} \begin{pmatrix} 5 & 1 & 0 & 0 & | & 9 \\ 0 & 8.6 & 1 & 0 & | & 2.4 \\ 0 & 0 & 8.8837 & 4 & | & 7.7209 \\ 0 & 0 & 0 & 2.6492 & | & 5.3927 \end{pmatrix} \xrightarrow{B_4 := -m_{43}B_3 + B_4}$$

Then we have:

$$\begin{aligned} 5x_1 + x_2 &= 9 \\ 8.6x_2 + x_3 &= 2.4 \\ 8.8837x_3 + 4x_4 &= 7.7209 \\ 2.6492x_4 &= 5.3927 \end{aligned}$$

Use backward subst. to get

$$\begin{aligned} x_4 &= 2.0356 \\ x_3 &= -0.0474 \quad \text{or } \mathbf{x} = \hat{\mathbf{x}} = (1.743, 0.285, -0.048, 2.036) \\ x_2 &= 0.2846 \\ x_1 &= 1.7431 \end{aligned}$$



Exercise:

Solve the following systems using Gauss elimination method with partial pivoting. Use 3 decimal places.

1.

$$\begin{aligned}2x_1 - x_2 + 7x_3 - x_4 &= -1 \\ -2x_1 + x_2 - 3x_3 - 8x_4 &= 3 \\ 8x_1 + 2x_2 - x_3 + 2x_4 &= -2 \\ x_1 - 8x_2 + x_3 - 2x_4 &= 4\end{aligned}$$

2.

$$\begin{pmatrix} 4 & 1 & -1 \\ 5 & 1 & 2 \\ 6 & 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} -2 \\ 4 \\ 6 \end{pmatrix}$$

Ans: 1.  $x_4 = -0.325$   $x_3 = -0.231$   $x_2 = -0.458$   $x_1 = -0.083$   
2.  $x_1 = 3$   $x_2 = -13$   $x_3 = 1$ .

## 2.2 LU FACTORIZATION METHOD

For a linear system

$$Ax = b$$

Use substitution of  $A = LU$ , where  $L$  is a **lower triangular matrix**, and  $U$  is **upper triangular matrix**.

$$LUx = b$$

Let

$$Ux = Y$$

Yields

$$LY = b$$

$$L = \begin{bmatrix} a & 0 & 0 & 0 \\ b & c & 0 & 0 \\ d & e & f & 0 \\ g & h & i & j \end{bmatrix}$$

$$U = \begin{bmatrix} k & l & m & n \\ 0 & u & p & q \\ 0 & 0 & r & s \\ 0 & 0 & 0 & t \end{bmatrix}$$

### Procedure:

Step 1: From  $A = LU$ , solve for  $L$  and  $U$ .

Step 2: From  $LY = b$ , solve for  $Y$  by forward substitution.

Step 3: From  $Ux = Y$ , solve for  $x$  by backward substitution.

### 2.2.1 Doolittle Method

$$A = LU$$

Diagonal element for matrix  $L = 1$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ b & 1 & 0 & 0 \\ d & e & 1 & 0 \\ g & h & i & 1 \end{bmatrix}$$

$$Ax = b$$

objective  $\rightarrow$  to get the value of  $x$

Step:

1.  $A = LU$ , find the matrix for  $L$  and  $U$
  2.  $Ly = b$ , solve for  $y$
  3.  $Ux = y$ , solve for  $x$
- } use backward and forward substitution

Example 3:

Solve this equation system using Doolittle method.

$$3x_1 + 2x_2 + 9x_3 = 28$$

$$2x_1 - x_2 + 6x_3 = 14$$

$$5x_1 + 2x_2 - 4x_3 = -13$$

Do the calculation in 4 decimal places.

Example 4:

Solve this equation system using Doolittle method.

$$2x_1 = 3$$

$$x_1 + 1.5x_2 = 4.5$$

$$-3x_2 + 0.5x_3 = -6.6$$

$$x_4 + x_3 + 2x_1 - 2x_2 - 0.8 = 0$$

### 2.2.2 Crout Method

$$A = LU$$

Diagonal element for matrix  $U = 1$

$$\begin{bmatrix} 1 & l & m & n \\ 0 & 1 & p & q \\ 0 & 0 & 1 & s \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$Ax = b$$

objective  $\rightarrow$  to find the value of  $x$

Step:

1.  $A = LU$ , determine  $L$  and  $U$

2.  $Ly = b$ , solve for  $y$

3.  $Ux = y$ , solve for  $x$

} use forward and backward

} substitutions

Example 5:

Solve this linear system using Crout method.

$$3x_1 + 2x_2 + 9x_3 = 28$$

$$2x_1 - x_2 + 6x_3 = 14$$

$$5x_1 + 2x_2 - 4x_3 = -13$$

## 2.2.3 Thomas Method

$$Ax = b$$

**Check this first!**

Make sure that matrix A must be **Tridiagonal Matrix**

$$\begin{bmatrix} d_1 & e_1 & 0 & \dots & 0 \\ c_2 & d_2 & e_2 & \ddots & \vdots \\ 0 & \ddots & \ddots & \ddots & 0 \\ \vdots & \ddots & c_{n-1} & d_{n-1} & e_{n-1} \\ 0 & 0 & 0 & c_n & d_n \end{bmatrix}$$

If not  $\rightarrow$  **rearrange the matrix**

$$L = \begin{bmatrix} \alpha_1 & 0 & 0 & 0 & 0 \\ c_2 & \alpha_2 & 0 & 0 & 0 \\ 0 & c_3 & \alpha_3 & 0 & 0 \\ 0 & 0 & \ddots & \ddots & 0 \\ 0 & 0 & 0 & c_n & \alpha_n \end{bmatrix} \quad U = \begin{bmatrix} 1 & \beta_1 & 0 & 0 & 0 \\ 0 & 1 & \beta_2 & 0 & 0 \\ 0 & 0 & 1 & \beta_3 & 0 \\ 0 & 0 & \ddots & \ddots & \beta_{n-1} \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$Ax = b$$

objective  $\rightarrow$  to find the value of  $x$

Step:

1.  $A = LU$ , determine the matrix for  $L$  and  $U$
  2.  $Lw = b$ , solve for  $y$
  3.  $Ux = w$ , solve for  $x$
- } use forward and backward substitutions

Example 6:

Solve this linear system equation using Thomas method.

$$\begin{bmatrix} 1 & 3 & 0 & 0 \\ 1 & 2 & 1 & 0 \\ 0 & 4 & -1 & -5 \\ 0 & 0 & 2 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \\ -20 \\ 11 \end{bmatrix}$$



## 2.2.4 Thomas Algorithm

Generalization of Thomas method

- suitable to solve large system
- Easy for programming coding

Remember! Always check whether Matrix A is tridiagonal matrix or not...

**Check this first!**

$$\begin{bmatrix} d_1 & e_1 & 0 & 0 & 0 \\ c_2 & d_2 & e_2 & 0 & 0 \\ 0 & c_3 & d_3 & e_3 & 0 \\ 0 & 0 & \dots & \dots & e_{n-1} \\ 0 & 0 & 0 & c_n & d_n \end{bmatrix}$$

If not → rearrange the matrix

$$\begin{bmatrix} d_1 & e_1 & 0 & 0 & 0 \\ c_2 & d_2 & e_2 & 0 & 0 \\ 0 & c_3 & d_3 & e_3 & 0 \\ 0 & 0 & \dots & \dots & e_{n-1} \\ 0 & 0 & 0 & c_n & d_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_n \end{bmatrix}$$

**Formula:**

Thomas's Algorithm:

$$\alpha_1 = d_1$$

$$\alpha_i = d_i - c_i \beta_{i-1}, \quad i = 2, 3, \dots, n$$

$$\beta_i = \frac{e_i}{\alpha_i}, \quad i = 1, 2, 3, \dots, n-1$$

$$y_1 = b_1 / \alpha_1$$

$$y_i = (b_i - c_i y_{i-1}) / \alpha_i, \quad i = 2, 3, \dots, n$$

$$x_n = y_n$$

$$x_i = y_i - \beta_i x_{i+1}, \quad i = n-1, n-2, \dots, 1$$

**Table:**

$i$	1	2	...	n
$d_i$				
$e_i$				
$c_i$				
$b_i$				
$\alpha_i$				
$\beta_i$				
$y_i$				
$x_i$				

Example 7:

Solve this linear system using Thomas method.

$$\begin{bmatrix} 1 & 3 & 0 & 0 \\ 1 & 2 & 1 & 0 \\ 0 & 4 & -1 & -5 \\ 0 & 0 & 2 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \\ -20 \\ 11 \end{bmatrix}$$

Example 8:

Given

$$3x_3 + 4x_4 = 8$$

$$2x_1 + 9x_2 + x_3 = 6$$

$$x_2 + 9x_3 + 4x_4 = 8$$

$$2x_1 + x_2 = 9$$

- (i) What condition that needs to be fulfilled before using Thomas's Algorithm?
- (ii) If the system above satisfied the condition, solve the equation system.

## 2.2.5 Cholesky Method

$$Ax = b$$

Matrix  $A$  must be **symmetric positive-definite**

### Definition

$$x^T Ax > 0, \quad \forall x \neq 0$$

### Rules (theorem)

1.  $|A| \neq 0$
2.  $a_{ii} > 0, \forall i = 1, 2, \dots, n$
3.  $\max_{\substack{1 \leq k \leq n \\ 1 \leq j \leq n}} |a_{kj}| \leq \max_{1 \leq i \leq n} |a_{ii}|$
4.  $(a_{ij})^2 < a_{ii}a_{jj}, \quad \forall \substack{i, j = 1, 2, \dots, n \\ i \neq j}$

$$A = LU$$

where  $U = L^T$

$$Ax = b$$

Target  $\rightarrow$  to find the value of  $x$

Step:

1.  $A = LU$ , determine  $L$  and  $U$
  2.  $Ly = b$ , solve for  $y$
  3.  $Ux = y$ , solve for  $x$
- } use forward and backward substitutions

Example 9:

Show that matrix  $A$  for the following linear system is symmetric positive-definite by using definition. Then, solve the system of linear equations by Cholesky Method.

$$4x_1 - x_2 + x_3 = 7$$

$$-x_1 + 7x_2 + 3x_3 = 6$$

$$x_1 + 3x_2 + 5x_3 = 1$$

## 2.3 ITERATIVE METHOD

Must satisfy convergence criterion i.e.  
A must be strictly diagonally dominant matrix

### Is A Strictly Diagonally Dominant Matrix?

$$|a_{ii}| > \sum_{\substack{j=1 \\ j \neq i}}^n |a_{ij}|$$

if not  $\rightarrow$  rearrange rows.

e.g.

Show that  $\begin{bmatrix} 3 & 2 & 0 \\ 2 & -5 & 1 \\ 1 & 2 & 7 \end{bmatrix}$  is a SDD matrix.

Solution:

$$B1: |3| > |2| + |0|$$

$$B2: |-5| > |2| + |1|$$

$$B3: |7| > |2| + |1|$$

### 2.3.1 Jacobi Method

**Formula:**

$$x_1^{(k+1)} = \frac{b_1 - a_{12}x_2^{(k)} - a_{13}x_3^{(k)}}{a_{11}}$$

$$x_2^{(k+1)} = \frac{b_2 - a_{21}x_1^{(k)} - a_{23}x_3^{(k)}}{a_{22}}$$

$$x_3^{(k+1)} = \frac{b_3 - a_{31}x_1^{(k)} - a_{32}x_2^{(k)}}{a_{33}}$$

**Initial guess:**  $x^{(0)} = (0 \ 0 \ \dots \ 0)^T$

**Stop the iteration when:**

$$\max_{1 \leq i \leq n} \left\{ \left| x_i^{(k)} - x_i^{(k-1)} \right| \right\} < \varepsilon$$

for a given value of  $\varepsilon$  and take  $\mathbf{X} \approx \mathbf{X}^{(k)}$

**Example 10:**

Solve the following linear system using Jacobi method.

Set  $\mathbf{X}^{(0)} = \mathbf{0}$ . Take  $\varepsilon = 0.05$ .

$$x_1 - 3x_2 + 12x_3 = 31$$

$$4x_1 + x_2 - x_3 = 3$$

$$2x_1 + 7x_2 + x_3 = 19$$

## Solution

Is matrix  $A$  SDD?

Rearrange rows :

$$4x_1 + x_2 - x_3 = 3$$

$$2x_1 + 7x_2 + x_3 = 19$$

$$x_1 - 3x_2 + 12x_3 = 31$$

The iteration formula:

$$x_1^{(k+1)} = \frac{3 - x_2^{(k)} + x_3^{(k)}}{4}$$

$$x_2^{(k+1)} = \frac{19 - 2x_1^{(k)} - x_3^{(k)}}{7}$$

$$x_3^{(k+1)} = \frac{31 - x_1^{(k)} + x_2^{(k)}}{12}$$

$k$	$x_1^{(k)}$	$x_2^{(k)}$	$x_3^{(k)}$	$ x_1^{(k)} - x_1^{(k-1)} $	$ x_2^{(k)} - x_2^{(k-1)} $	$ x_3^{(k)} - x_3^{(k-1)} $
0	0	0	0			
1						
2						
3						
4						
5						

$$\|\mathbf{x}^{(5)} - \mathbf{x}^{(4)}\| = \max_{1 \leq i \leq 3} \left\{ |x_i^{(5)} - x_i^{(4)}| \right\}$$

$$= \max \{0.01, 0.01, 0.01\} = 0.01 < \varepsilon$$

$$\therefore \mathbf{x} \approx \mathbf{x}^{(5)} = (1.01, 2.00, 3.00)$$



## 2.3.2 Gauss Seidel Method

**Formula:**

$$x_1^{(k+1)} = \frac{b_1 - a_{12}x_2^{(k)} - a_{13}x_3^{(k)}}{a_{11}}$$

$$x_2^{(k+1)} = \frac{b_2 - a_{21}x_1^{(k+1)} - a_{23}x_3^{(k)}}{a_{22}}$$

$$x_3^{(k+1)} = \frac{b_3 - a_{31}x_1^{(k+1)} - a_{32}x_2^{(k+1)}}{a_{33}}$$

**Initial guess:**  $x^{(0)} = (0 \ 0 \ \dots \ 0)^T$

**Stop the iteration when:**

$$\max_{1 \leq i \leq n} \left\{ \left| x_i^{(k+1)} - x_i^{(k)} \right| \right\} < \varepsilon$$

for a given value of  $\varepsilon$  and take  $\mathbf{X} \approx \mathbf{X}^{(k)}$

**Example 11:**

Solve the following linear system using Gauss-Seidel method.

Set  $\mathbf{x}^{(0)} = \mathbf{0}$ . Take  $\varepsilon = 0.05$ .

$$x_1 - 3x_2 + 12x_3 = 31$$

$$4x_1 + x_2 - x_3 = 3$$

$$2x_1 + 7x_2 + x_3 = 19$$

## Solution

Is matrix  $A$  SDD?

Rearrange rows :

$$4x_1 + x_2 - x_3 = 3$$

$$2x_1 + 7x_2 + x_3 = 19$$

$$x_1 - 3x_2 + 12x_3 = 31$$

The iteration formula:

$$x_1^{(k+1)} = \frac{3 - x_2^{(k)} + x_3^{(k)}}{4}$$

$$x_2^{(k+1)} = \frac{19 - 2x_1^{(k+1)} - x_3^{(k)}}{7}$$

$$x_3^{(k+1)} = \frac{31 - x_1^{(k+1)} + x_2^{(k+1)}}{12}$$

$k$	$x_1^{(k)}$	$x_2^{(k)}$	$x_3^{(k)}$	$ x_1^{(k)} - x_1^{(k-1)} $	$ x_2^{(k)} - x_2^{(k-1)} $	$ x_3^{(k)} - x_3^{(k-1)} $
0	0	0	0			
1						
2						
3						
4						

$$\begin{aligned}\|\mathbf{x}^{(4)} - \mathbf{x}^{(3)}\| &= \max_{1 \leq i \leq 3} \left\{ |x_i^{(4)} - x_i^{(3)}| \right\} \\ &= \max \{0.00, 0.00, 0.00\} = 0.00 < \varepsilon\end{aligned}$$

$$\therefore \mathbf{x} \approx \mathbf{x}^{(5)} = (1.00, 2.00, 3.00)$$

Exercise:

1. Write the Gauss - Seidel formula for

$$5x_1 - x_2 + x_3 = 11$$

$$2x_1 + 8x_2 - x_3 = 17$$

$$-x_1 + x_2 + 7x_3 = 21$$

Then find the value of  $x_1$ ,  $x_2$ , and  $x_3$ . Do the calculation in 3 decimal places.

2. Solve the following system using Gauss - Seidel method and stop the iteration when  $\|\mathbf{x}^{(k)} - \mathbf{x}^{(k-1)}\|_{\infty} < 0.0005$ .

$$\begin{bmatrix} 10 & -1 & 2 & 0 \\ -1 & 11 & -1 & 3 \\ 2 & -1 & 10 & -1 \\ 0 & 3 & -1 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 6 \\ 25 \\ -11 \\ 15 \end{bmatrix}$$