

*Network properties*

L	number of links in a network; network sum continuity = $\Sigma l$
C	network sum connectivity = $\Sigma c$
D	network sum depth = $\Sigma d$
S	sum value of a network (= L + C + D)
R	number of routes
Y	number of types of route
D'	maximum depth value of network

*Netgram properties*

$\Lambda$	relative continuity = L/S
X	relative connectivity = C/S
$\Delta$	relative depth = D/S
$\Lambda + X + \Delta = 1$	
<i>Hetgram properties</i>	
$\Psi$	irregularity = Y/R
$\Phi$	regularity = $1 - \Psi$
$\Theta$	recursivity = D'/R
$\Omega$	complexity = (Y - D')/R
$\Phi + \Theta + \Omega = 1$	

*Properties for Bayswater network*

Network properties (Table 5.1)				Netgram values (Figure 6.4)		Hetgram values (Figure 6.12)	
L	73	R	27	$\Lambda$	0.28	$\Phi$	0.26
C	112	Y	20	X	0.42	$\Theta$	0.15
D	79	D'	4	$\Delta$	0.30	$\Omega$	0.59
S	264				1.00		1.00

For the Bayswater network (Figure 5.13), there are 41 T-junctions ( $J_3 = 41$ ) and 5 crossroads ( $J_4 = 5$ ). Hence  $P = p_3^{41} p_4^5 = (3^{41} \times 6^5) = 283,614,019,828,880,035,069,728$ .

**A6.3 The Netgram**

Each plotted point on the netgram represents a whole *network* (route structure). For each position on the netgram,  $\Lambda + X + \Delta = 1$ . On the bottom axis, where  $\Delta = 0$ ,  $\Lambda = (1 - X)$ . Each position on the netgram can be expressed in terms of three parameters ( $\Lambda$ , X,  $\Delta$ ) or simply two parameters (X,  $\Delta$ ). The notation (X,  $\Delta$ ) is convenient as it echoes the Cartesian pair of 'along' and 'up' (X, Y). A set of reference lines (shown in grey) may be used to conveniently locate positions on the netgram, using simple relationships between  $\Lambda$ , X and  $\Delta$ . Point O ( $\frac{1}{4}, \frac{1}{2}$ ) is the position of a single link network (L = 1, C = 0, D = 1). Point P is ( $\frac{1}{3}, \frac{1}{3}$ ); point Q is ( $\frac{1}{2}, \frac{1}{3}$ ). The grid of reference lines could be equated with the 'rhumb lines' on a navigational chart (Wilford, 2000) or reseau (reference lines on a star map, etc.).