CARTESIAN VECTORS AND THEIR ADDITION & SUBTRACTION

Today's Objectives:

Students will be able to:

- a) Represent a 3-D vector in a Cartesian coordinate system.
- b) Find the magnitude and coordinate angles of a 3-D vector
- c) Add vectors (forces) in 3-D space



In-Class Activities:

- Reading Quiz
- Applications/Relevance
- A Unit Vector
- 3-D Vector Terms
- Adding Vectors
- Example Problem
- Concept Quiz
- Group Problem
- Attention Quiz

READING QUIZ

1. Vector algebra, as we are going to use it, is based on a coordinate system.

- A) EuclideanB) Left-handedC) GreekD) Right-handedEgyptian
- 2. The symbols α , β , and γ designate the ______ of a 3-D Cartesian vector.
 - A) Unit vectors B) Coordinate direction angles
 - C) Greek societies D) X, Y and Z components

APPLICATIONS



Many structures and machines involve 3dimensional space.

In this case, the power pole has guy wires helping to keep it upright in high winds. How would you represent the forces in the cables using Cartesian vector form? In the case of this radio tower, if you know the forces in the three cables, how would you determine the resultant force acting at D, the top of the tower?



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CARTESIAN UNIT VECTORS

For a vector \boldsymbol{A} , with a magnitude of A, an unit vector is defined as

 $\boldsymbol{u}_A = \boldsymbol{A} / \boldsymbol{A}$.

Characteristics of a unit vector :

a) Its magnitude is 1.

- b) It is dimensionless (has no units).
- c) It points in the same direction as the original vector (*A*).

The unit vectors in the Cartesian axis system are i, j, and k. They are unit vectors along the positive x, y, and z axes respectively.





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CARTESIAN VECTOR REPRESENTATION



Consider a box with sides A_X , A_Y , and A_Z meters long.

The vector **A** can be defined as

$$\boldsymbol{A} = (A_X \, \boldsymbol{i} + A_Y \, \boldsymbol{j} + A_Z \, \boldsymbol{k}) \, m$$

The projection of vector *A* in the x-y plane is A'. The magnitude of A' is found by using the same approach as a 2-D vector: $A' = (A_X^2 + A_Y^2)^{1/2}$.

The magnitude of the position vector \mathbf{A} can now be obtained as

$$A = ((A')^2 + A_Z^2)^{\frac{1}{2}} = (A_X^2 + A_Y^2 + A_Z^2)^{\frac{1}{2}}$$

DIRECTION OF A CARTESIAN VECTOR

The direction or orientation of vector \mathbf{A} is defined by the angles α , β , and α

the angles α , β , and γ .

These angles are measured between the vector and the positive X, Y and Z axes, respectively. Their range of values are from 0° to 180°

Using trigonometry, "direction cosines" are found using

$$\cos \alpha = \frac{A_x}{A} \quad \cos \beta = \frac{A_y}{A} \quad \cos \gamma = \frac{A_z}{A}$$



These angles are not independent. They must satisfy the following equation.

$$\cos^2\alpha + \cos^2\beta + \cos^2\gamma = 1$$

This result can be derived from the definition of a coordinate direction angles and the unit vector. Recall, the formula for finding the unit vector of any position vector: $A = A_x = A_y$

$$\mathbf{u}_A = \frac{\mathbf{A}}{A} = \frac{A_x}{A}\mathbf{i} + \frac{A_y}{A}\mathbf{j} + \frac{A_z}{A}\mathbf{k}$$

or written another way, $u_A = \cos \alpha i + \cos \beta j + \cos \gamma k$.

ADDITION OF CARTESIAN VECTORS (Section 2.6)

Once individual vectors are written in Cartesian form, it is easy to add or subtract them. The process is essentially the same as when 2-D vectors are added.

$$\mathbf{F}_{R} = \Sigma \mathbf{F} = \Sigma F_{x} \mathbf{i} + \Sigma F_{y} \mathbf{j} + \Sigma F_{z} \mathbf{k}$$

For example, if

 $A = A_X \mathbf{i} + A_Y \mathbf{j} + A_Z \mathbf{k} \text{ and}$ $B = B_X \mathbf{i} + B_Y \mathbf{j} + B_Z \mathbf{k}, \text{ then}$ $A + B = (A_X + B_X) \mathbf{i} + (A_Y + B_Y) \mathbf{j} + (A_Z + B_Z) \mathbf{k}$ or

$$\boldsymbol{A} - \boldsymbol{B} = (A_X - B_X) \boldsymbol{i} + (A_Y - B_Y) \boldsymbol{j} + (A_Z - B_Z) \boldsymbol{k}$$

IMPORTANT NOTES

Sometimes 3-D vector information is given as:

- a) Magnitude and the coordinate direction angles, or,
- b) Magnitude and projection angles.

You should be able to use both these sets of information to change the representation of the vector into the Cartesian form, i.e.,

 $\mathbf{F} = \{10 \, \mathbf{i} - 20 \, \mathbf{j} + 30 \, \mathbf{k}\} \, \mathrm{N}$.

EXAMPLE



Plan:

- 1) Using geometry and trigonometry, write F_1 and F_2 in Cartesian vector form.
- 2) Then add the two forces (by adding x and y-components).

EXAMPLE (continued)

Solution:

First, resolve force F_1 .

$$F_x = 0 = 0 N$$

 $F_y = 500 (4/5) = 400 N$
 $F_z = 500 (3/5) = 300 N$



Now, write F_1 in Cartesian vector form (don't forget the units!).

 $F_1 = \{0 \ i + 400 \ j + 300 \ k\} \ N$

EXAMPLE (continued)

Now, resolve force F_2 . $F_{2z} = -800 \sin 45^\circ = -565.7 \text{ N}$ $F_2' = 800 \cos 45^\circ = 565.7 \text{ N}$

 F_2 ' can be further resolved as, $F_{2x} = 565.7 \cos 30^\circ = 489.9 \text{ N}$ $F_{2y} = 565.7 \sin 30^\circ = 282.8 \text{ N}$



Thus, we can write:

 $F_2 = \{489.9 \, i + 282.8 \, j - 565.7 \, k \}$ N

EXAMPLE (continued)



So $F_R = F_1 + F_2$ and $F_1 = \{0 \ i + 400 \ j + 300 \ k\}$ N $F_2 = \{489.9 \ i + 282.8 \ j - 565.7 \ k\}$ N $F_R = \{490 \ i + 683 \ j - 266 \ k\}$ N

CONCEPT QUIZ

- 1. If you know only u_A , you can determine the _____ of A uniquely.
 - A) magnitudeB) angles (α , β and γ)C) components (A_X , A_Y , & A_Z)D) All of the above.
- 2. For a force vector, the following parameters are randomly generated. The magnitude is 0.9 N, $\alpha = 30^{\circ}$, $\beta = 70^{\circ}$, $\gamma = 100^{\circ}$. What is <u>wrong</u> with this 3-D vector ?
 - A) Magnitude is too small.
 - B) Angles are too large.
 - C) All three angles are arbitrarily picked.
 - D) All three angles are between 0° to 180° .

GROUP PROBLEM SOLVING



Given: The screw eye is subjected to two forces, F_1 and F_2 .

The magnitude and the coordinate direction angles of the resultant force.

1) Using the geometry and trigonometry, resolve and write F_1 and F_2 in the Cartesian vector form.

2) Add F_1 and F_2 to get F_R .

3) Determine the magnitude and angles α , β , γ .

GROUP PROBLEM SOLVING (continued)



First resolve the force F_1 . $F_{1z} = -250 \sin 35^\circ = -143.4 \text{ N}$ $F' = 250 \cos 35^\circ = 204.8 \text{ N}$ F' can be further resolved as, $F_{1x} = 204.8 \sin 25^\circ = 86.6 \text{ N}$ $F_{1y} = 204.8 \cos 25^\circ = 185.6 \text{ N}$

Now we can write:

 $F_1 = \{86.6 i + 185.6 j - 143.4 k\}$ N

GROUP PROBLEM SOLVING (continued)



Now, resolve force F_2 .

The force F_2 can be represented in the Cartesian vector form as: $F_2 = 400\{ \cos 120^\circ i + \cos 45^\circ j + \cos 60^\circ k \} N$ $= \{ -200 i + 282.8 j + 200 k \} N$ $F_2 = \{ -200 i + 282.8 j + 200 k \} N$

GROUP PROBLEM SOLVING (continued)



So
$$F_R = F_1 + F_2$$
 and
 $F_1 = \{ 86.6 i + 185.6 j - 143.4 k \}$ N
 $F_2 = \{ -200 i + 282.8 j + 200 k \}$ N
 $F_R = \{ -113.4 i + 468.4 j + 56.6 k \}$ N

Now find the magnitude and direction angles for the vector. $F_{R} = \{(-113.4)^{2} + 468.4^{2} + 56.6^{2}\}^{1/2} = 485.2 = \underline{485 N}$ $\alpha = \cos^{-1} (F_{Rx} / F_{R}) = \cos^{-1} (-113.4 / 485.2) = \underline{104^{\circ}}$ $\beta = \cos^{-1} (F_{Ry} / F_{R}) = \cos^{-1} (468.4 / 485.2) = \underline{15.1^{\circ}}$ $\gamma = \cos^{-1} (F_{Rz} / F_{R}) = \cos^{-1} (56.6 / 485.2) = \underline{83.3^{\circ}}$

ATTENTION QUIZ

- 1. What is <u>not true</u> about an unit vector, e.g., u_A ?
 - A) It is dimensionless.
 - B) Its magnitude is one.
 - C) It always points in the direction of positive X- axis.
 - D) It always points in the direction of vector A.
- 2. If $\mathbf{F} = \{10 \, \mathbf{i} + 10 \, \mathbf{j} + 10 \, \mathbf{k}\}$ N and

 $G = \{20 i + 20 j + 20 k \}$ N, then $F + G = \{$ _____ $\}$ N

- A) 10i + 10j + 10k
- B) 30 i + 20 j + 30 k
- C) -10i 10j 10k

D) 30i + 30j + 30k

End of the Lecture

Learning Continue

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