# **MOMENT ABOUT AN AXIS**

# Today's Objectives:

Students will be able to determine the moment of a force about an axis using <u>In-Class Activities</u>:

- a) scalar analysis, and,
- b) vector analysis.



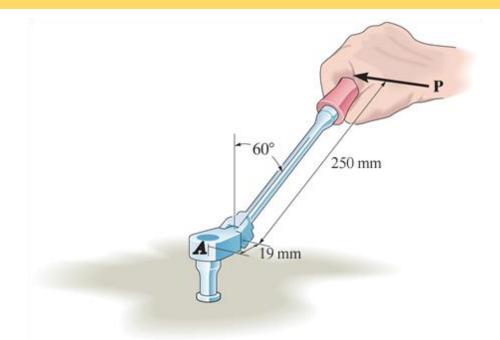
- Check Homework
- Reading Quiz
- Applications
- Scalar Analysis
- Vector Analysis
- Example Problem
- Concept Quiz
- Group Problem Solving
- Attention Quiz

# **READING QUIZ**

- 1. When determining the moment of a force about a specified axis, the axis must be along \_\_\_\_\_.
  - A) the x axis B) the y axis C) the z axis
  - D) any line in 3-D space E) any line in the x-y plane

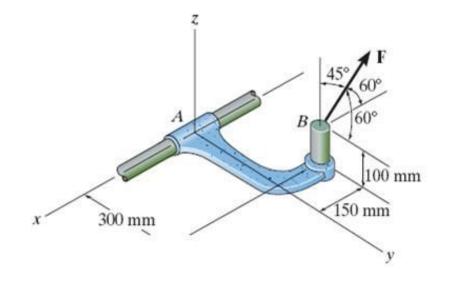
- 2. The triple scalar product  $\boldsymbol{u} \cdot (\boldsymbol{r} \times \boldsymbol{F})$  results in
  - A) a scalar quantity (+ or ). B) a vector quantity.
  - C) zero. D) a unit vector.
  - E) an imaginary number.

#### **APPLICATIONS**



With the force P, a person is creating a moment  $M_A$  using this flex-handle socket wrench. Does all of  $M_A$  act to turn the socket? How would you calculate an answer to this question?

#### **APPLICATIONS (continued)**



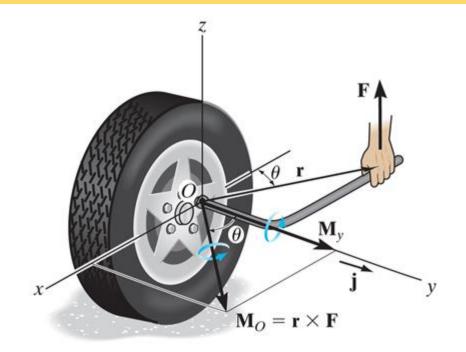
Sleeve A of this bracket can provide a maximum resisting moment of 125 N·m about the x-axis. How would you determine the maximum magnitude of  $\mathbf{F}$  before turning about the x-axis occurs?

## **SCALAR ANALYSIS**

Recall that the moment of a scalar force about any point O is  $M_O = F d_O$  where  $d_O$  is the perpendicular (or shortest) distance from the point to the <u>force's line of action</u>. This concept can be extended to find the moment of a force about an axis.

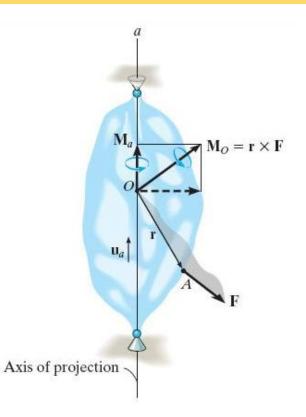
Finding the moment of a force about an axis can help answer the types of questions we just considered.

### **SCALAR ANALYSIS (continued)**



In the figure above, the moment about the y-axis would be  $M_y = F_z (d_x) = F (r \cos \theta)$ . However, unless the force can easily be broken into components and the "d<sub>x</sub>" found quickly, such calculations are not always trivial and vector analysis may be much easier (and less likely to produce errors).

### **VECTOR ANALYSIS**



Our goal is to find the moment of **F** (the tendency to rotate the body) about the *a*-axis.

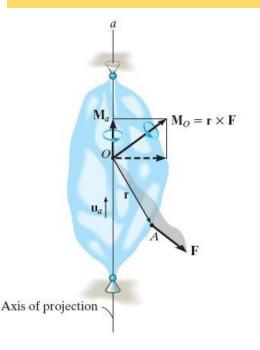
First compute the moment of  $\mathbf{F}$  about any arbitrary point O that lies on the *a*-axis using the cross product.

 $M_o = r \times F$ 

Now, find the component of  $M_0$  along the *a*-axis using the dot product.

$$\mathbf{M}_a = \boldsymbol{u}_a \boldsymbol{\cdot} \boldsymbol{M}_{\boldsymbol{O}}$$

## **VECTOR ANALYSIS (continued)**



 $M_a$  can also be obtained as

$$M_a = \mathbf{u}_a \cdot (\mathbf{r} \times \mathbf{F}) = \begin{vmatrix} u_{a_x} & u_{a_y} & u_{a_z} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}$$

The above equation is also called the <u>triple scalar product</u>.

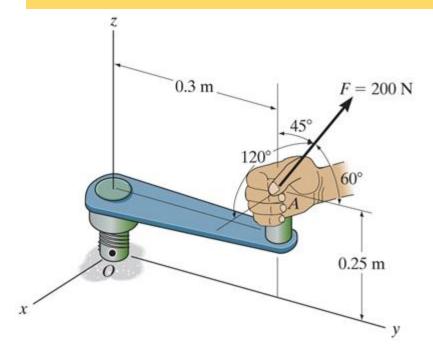
### In the this equation,

 $u_a$  represents the unit vector along the *a*-axis,

*r* is the position vector from any point on the *a*-axis to any point A on the line of action of the force, and

**F** is the force vector.

### EXAMPLE



**Given:** A force is applied to the tool as shown.

**Find:** The magnitude of the moment of this force about the x axis of the value.

**Plan:** 

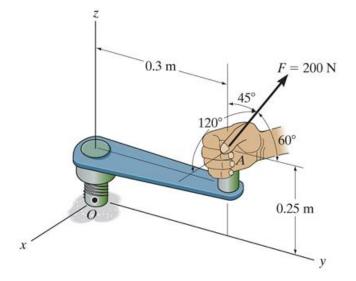
- 1) Use  $M_z = \boldsymbol{u} \cdot (\boldsymbol{r} \times \boldsymbol{F})$ .
- 2) First, find **F** in Cartesian vector form.
- 3) Note that u = 1 i in this case.
- 4) The vector *r* is the position vector from O to A.

## **EXAMPLE** (continued)

## **Solution**:

u = 1 i  $r_{OA} = \{0 i + 0.3 j + 0.25 k\} m$  $F = 200 (\cos 120 i + \cos 60 j + \cos 45 k) N$ 

 $= \{-100 \, \mathbf{i} + 100 \, \mathbf{j} + 141.4 \, \mathbf{k}\} \, \mathrm{N}$ 



Now find 
$$M_z = \mathbf{u} \cdot (\mathbf{r}_{OA} \times \mathbf{F})$$
  
 $M_z = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 0.3 & 0.25 \\ -100 & 100 & 141.4 \end{vmatrix} = 1\{0.3 (141.4) - 0.25 (100)\} \text{ N} \cdot \text{m}$ 

 $\underline{M}_{z} = 17.4 \text{ N} \cdot \text{m CCW}$ 

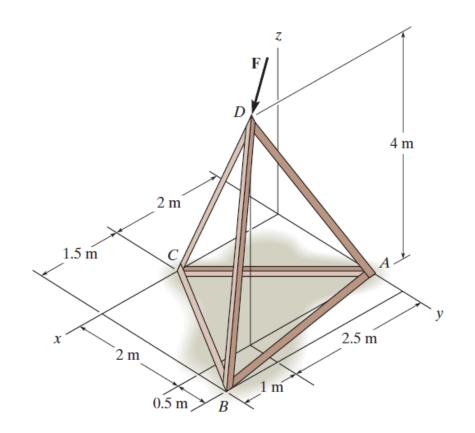
## **CONCEPT QUIZ**

- 1. The vector operation  $(\mathbf{P} \times \mathbf{Q}) \bullet \mathbf{R}$  equals
  - A)  $\boldsymbol{P} \times (\boldsymbol{Q} \bullet \boldsymbol{R}).$
  - B)  $\boldsymbol{R} \bullet (\boldsymbol{P} \times \boldsymbol{Q}).$
  - C)  $(\mathbf{P} \bullet \mathbf{R}) \times (\mathbf{Q} \bullet \mathbf{R})$ .
  - D)  $(\mathbf{P} \times \mathbf{R}) \bullet (\mathbf{Q} \times \mathbf{R})$ .

## **CONCEPT QUIZ (continued)**

- 2. The force *F* is acting along DC. Using the triple scalar product to determine the moment of *F* about the bar BA, you could use any of the following position vectors except \_\_\_\_\_.
  - A)  $r_{BC}$ B)  $r_{AD}$ C)  $r_{AC}$ D)  $r_{DB}$

E) **r**<sub>BD</sub>



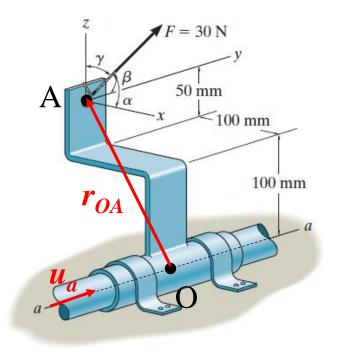
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### **GROUP PROBLEM SOLVING**

- Given: The force of F = 30 N acts on the bracket.  $\alpha = 60^{\circ}, \beta = 60^{\circ}, \gamma = 45^{\circ}.$
- **Find**: The moment of *F* about the a-a axis.

#### **Plan**:

Find *u<sub>a</sub>* and *r<sub>OA</sub>* Find *F* in Cartesian vector form.
 Use M<sub>a</sub> = *u<sub>a</sub>* • (*r<sub>OA</sub>* × *F*)



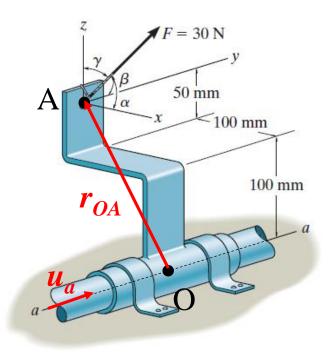
#### **GROUP PROBLEM SOLVING (continued)**

#### **Solution**:

$$u_a = j$$
  
 $r_{OA} = \{-0.1 \ i + 0.15 \ k\} \ m$ 

$$F = 30 \{\cos 60^{\circ} i + \cos 60^{\circ} j + \cos 45^{\circ} k\} N$$

 $F = \{ 15 i + 15 j + 21.21 k \}$  N

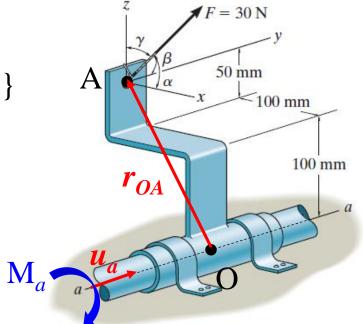


#### **GROUP PROBLEM SOLVING (continued)**

Now find the triple product,  $M_a = u_a \cdot (r_{OA} \times F)$ 

$$M_a = \begin{vmatrix} 0 & 1 & 0 \\ -0.1 & 0 & 0.15 \\ 15 & 15 & 21.21 \end{vmatrix}$$
 N·m

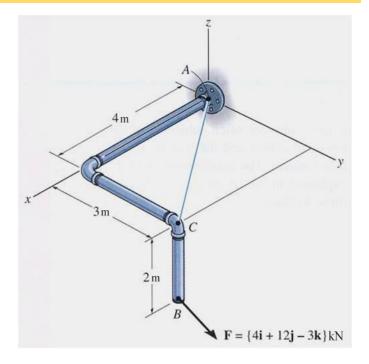
$$M_a = -1 \{-0.1 \ (21.21) - 0.15 \ (15)\}$$
$$= \underline{4.37 \ N \cdot m}$$



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## **ATTENTION QUIZ**

- For finding the moment of the force *F* about the x-axis, the position vector in the triple scalar product should be \_\_\_\_.
  - A)  $r_{AC}$ B)  $r_{BA}$ C)  $r_{AB}$ D)  $r_{BC}$



2. If *r* = {1 *i* + 2 *j*} m and *F* = {10 *i* + 20 *j* + 30 *k*} N, then the moment of *F* about the y-axis is \_\_\_\_\_ N ⋅ m.
A) 10 B) -30
C) -40 D) None of the above.

End of the Lecture

Learning Continue

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