



5.7 Constraints and Statical Determinacy

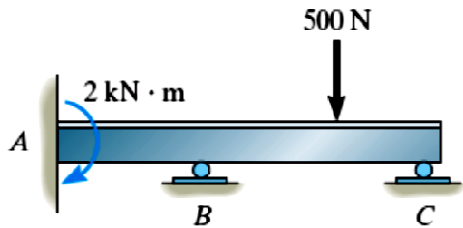
- To ensure the equilibrium of a rigid body, the body must also be properly held or constrained by its supports.

□ Redundant Constraints

- A body is said to have redundant constraints if it has more supports than are necessary to hold it in equilibrium.
- A body with redundant constraints is *statically indeterminate* as there are more unknown loadings than equations of equilibrium.

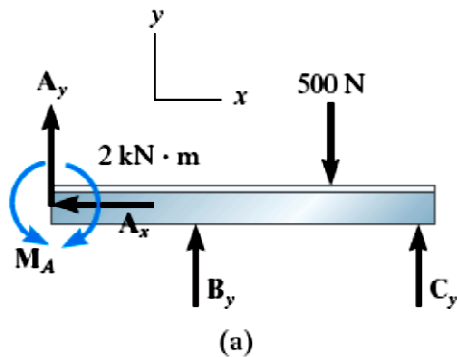
▪ **Examples of statically indeterminate problems.**

(i)



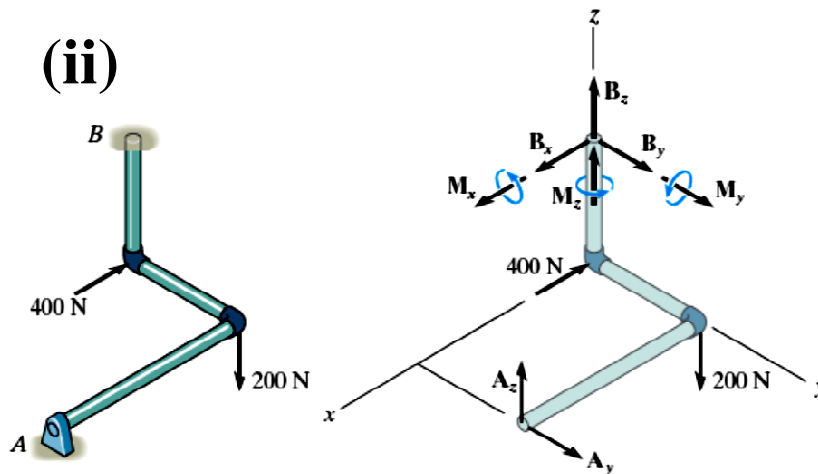
No. of equilibrium equations = 3

No. of unknowns = 5



(a)

(ii)



No. of equilibrium equations = 6

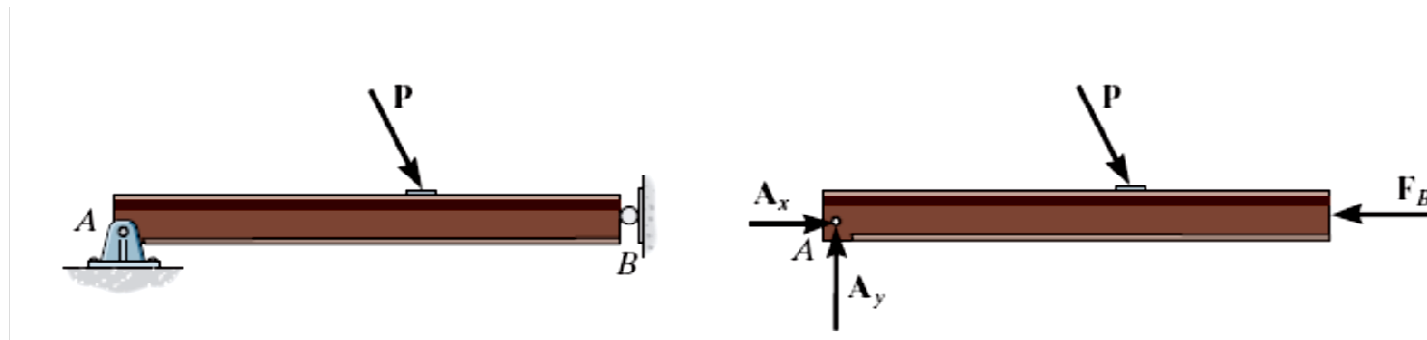
No. of unknowns = 8



□ Improper Constraints

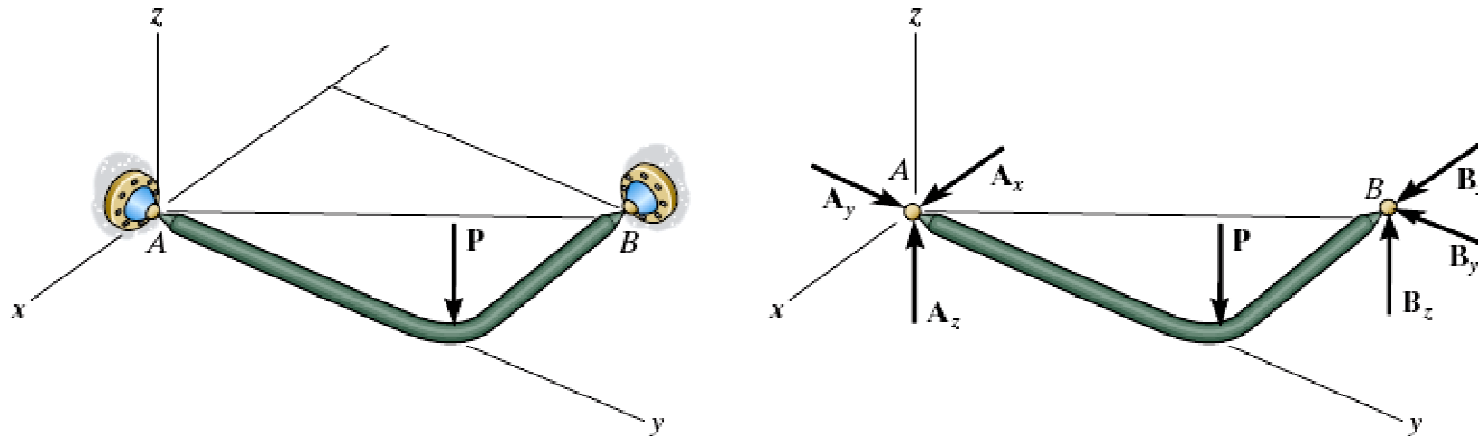
- Having the same number of unknowns as the available equations of equilibrium does not always guarantee that a body will be stable when subjected to a particular loading.
- Instability may occur in a rigid body if it is *improperly constrained* by its supports.
- A body is considered *improperly constrained* if
 - (1) all the reactive forces intersect at a common point (2-D case) or pass through a common axis (3-D case),
 - (2) all the reactive forces are parallel.
 - (3) the body is partially constrained.

(1.a) 2-D Case: All reactive forces intersect at a common point



- The reactive forces A_x , A_y , and F_B are concurrent at point A. Therefore, the moments of these forces about A are zero.
- However, the presence of \mathbf{P} causes $\sum M_A \neq 0$.
- Consequently, the beam will rotate about A.
- So, the beam is improperly constrained.

(1.b) 3-D Case: : All reactive forces pass through a common axis

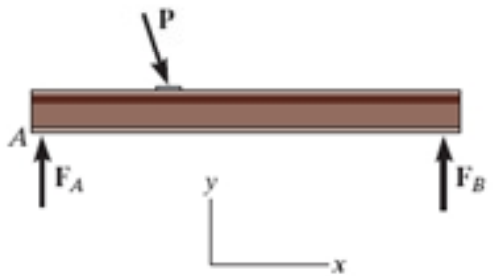
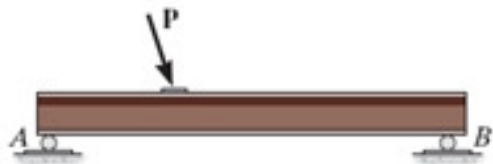


- The reactive forces at the ball-and socket supports A_x , A_y , A_z , B_x , B_y , and B_z , pass through the common axis AB .

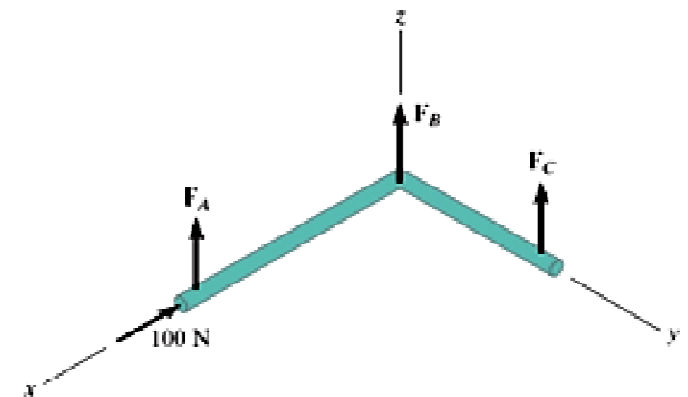
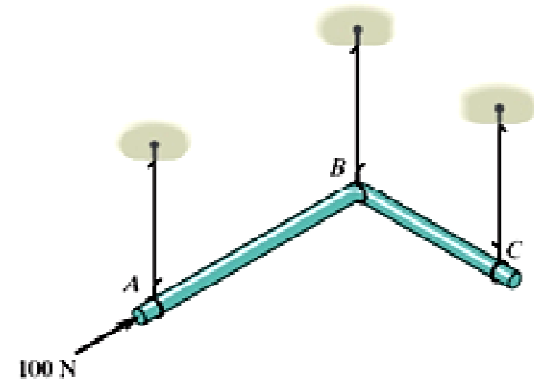
Therefore, the moments of these forces about A & B are all zero.

- However, the presence of \mathbf{P} causes $\sum M_{AB} \neq 0$.
- Consequently, the member will rotate about the AB axis.
- So, the member is improperly constrained.

(2) All reactive forces are parallel



(a) 2 D case

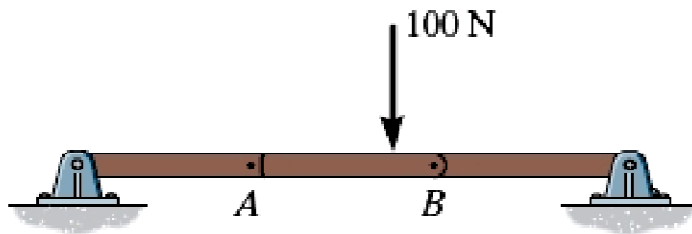


(b) 3-D case

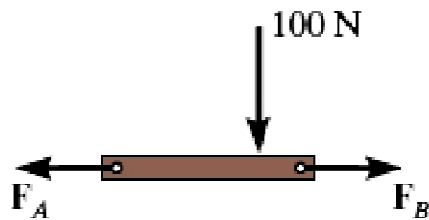
$$\sum F_x \neq 0.$$

(3) A Partially Constrained Body

A body is partially constrained if it has fewer reactive forces than equations of equilibrium that must be satisfied.



(a)



(b)

$$\sum F_x = 0$$

$$\sum F_y \neq 0$$