Supplementary File for Conjugate Momentum Quadratic Penalty Alternating Minimization for Total Variation Image Restoration

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I. Test Images

This section serves as an appendix, providing details and results that complement the main file. Figure 1 shows are the tested images used for the experiments that discussed in the subsection V-A.





(a) *Foot* (512×512)

(b) *Pepper* (512×512)



(c) Cameraman (256 \times 256)

Fig. 1: Test images used

II. TABLES

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Table I, provided here presents the comparative results between QPAM, AQPAM, and CG-QPAM under Gaussian and Poisson noise conditions, as discussed in subsection V-C of the main paper.

III. RESTORED IMAGES

Figure 2 shows the results of the SSIM between QPAM and CG-QPAM for BSNR 30 that discussed in V-C-1.

IV. FIGURES OF CG-QPAM CONVERGENCE

Figure 3 shows the effects of convergence of CG-QPAM if the parameter α are modified that discussed in the V-C-1.

BSNR	Image	Method	PSNR	SSIM	Time (s)	Itı
20	Pepper	QPAM	29.665	0.799	3.337	14
		AQPAM	29.282	0.789	2.812	11
		CG-QPAM	29.829	0.812	2.763	10
	Foot	QPAM	27.690	0.725	5.726	25
		AQPAM	27.132	0.701	3.966	17
		CG-QPAM	27.720	0.732	5.965	25
	Cameraman	QPAM	24.953	0.749	0.901	19
	cuncrantar	AQPAM	24.734	0.751	0.619	13
		CG-QPAM	24.976	0.775	1.010	18
30	Pepper	QPAM	32.332	0.841	2.746	10
		AQPAM	31.951	0.838	3.469	98
		CG-QPAM	31.058	0.847	1.968	7 4
	Foot	QPAM	29.997	0.831	4.475	19
	1001	AQPAM	29.439	0.829	3.223	14
		CG-QPAM	29.076	0.874	3.616	14
	Camanan	ODAM	27.149	0 626	0.002	15
	Cameraman	QPAM AOPAM		0.828	0.886	15
40		AQPAM CG-QPAM	27.131 25.526	0.828 0.802	0.501 0.482	119 11
	P					
	Pepper	QPAM AODAM	34.456	0.877	1.890	77
		AQPAM CG-QPAM	34.090 30.513	$0.875 \\ 0.821$	1.766 0.456	73 11
		CO-QPAM	50.515	0.821	0.450	11
	Foot	QPAM	32.787	0.905	3.707	15
		AQPAM	32.155	0.904	2.532	11
		CG-QPAM	29.953	0.904	1.386	30
	Cameraman	QPAM	30.007	0.890	0.726	14
		AQPAM	29.992	0.890	0.387	- 98
		CG-QPAM	25.076	0.765	0.088	17
		(a) Gauss	ian Noise	:		
		(a) Gauss				
Pixel	Image	Method	PSNR	SSIM	Time (s)	Itr
Pixel	Image Penner	Method			Time (s) 9.394	
	Image Pepper	Method QPAM	27.584	0.761	9.394	170
Pixel 255	-	Method				170
	Pepper	Method QPAM AQPAM CG-QPAM	27.584 27.113 24.968	0.761 0.750 0.734	9.394 4.658 0.301	170 154 9
	-	Method QPAM AQPAM	27.584 27.113	0.761 0.750	9.394 4.658	170 154 9 279
	Pepper	Method QPAM AQPAM CG-QPAM QPAM	27.584 27.113 24.968 27.123	0.761 0.750 0.734 0.876	9.394 4.658 0.301 7.434	170 154 9 279
	Pepper Foot	Method QPAM AQPAM CG-QPAM QPAM AQPAM CG-QPAM	27.584 27.113 24.968 27.123 26.484	0.761 0.750 0.734 0.876 0.870 0.836	9.394 4.658 0.301 7.434 5.633 0.251	170 154 9 279 194 5
	Pepper	Method QPAM AQPAM CG-QPAM QPAM AQPAM	27.584 27.113 24.968 27.123 26.484 24.833	0.761 0.750 0.734 0.876 0.870	9.394 4.658 0.301 7.434 5.633	170 154 9 279 194 5 211
	Pepper Foot	Method QPAM AQPAM CG-QPAM QPAM AQPAM CG-QPAM QPAM	27.584 27.113 24.968 27.123 26.484 24.833 23.849	 0.761 0.750 0.734 0.876 0.870 0.836 0.720 	9.394 4.658 0.301 7.434 5.633 0.251 1.079	170 154 9 279 194 5 211
255	Pepper Foot	Method QPAM AQPAM CG-QPAM AQPAM CG-QPAM AQPAM AQPAM CG-QPAM QPAM	27.584 27.113 24.968 27.123 26.484 24.833 23.849 23.704 24.833 24.075	0.761 0.750 0.734 0.876 0.870 0.836 0.720 0.720 0.836 0.720 0.836	9.394 4.658 0.301 7.434 5.633 0.251 1.079 0.847 0.251 4.881	170 154 9 279 194 5 211 166 5
	Pepper Foot Cameraman	Method QPAM AQPAM CG-QPAM AQPAM CG-QPAM QPAM AQPAM CG-QPAM AQPAM QPAM	27.584 27.113 24.968 27.123 26.484 24.833 23.849 23.704 24.833 24.075 23.534	0.761 0.750 0.734 0.876 0.870 0.836 0.720 0.836 0.720 0.836 0.670 0.656	9.394 4.658 0.301 7.434 5.633 0.251 1.079 0.847 0.251 4.881 4.372	170 154 9 279 194 5 211 166 5 174
255	Pepper Foot Cameraman	Method QPAM AQPAM CG-QPAM AQPAM CG-QPAM AQPAM AQPAM CG-QPAM QPAM	27.584 27.113 24.968 27.123 26.484 24.833 23.849 23.704 24.833 24.075	0.761 0.750 0.734 0.876 0.870 0.836 0.720 0.720 0.836 0.720 0.836	9.394 4.658 0.301 7.434 5.633 0.251 1.079 0.847 0.251 4.881	170 154 9 279 194 5 211 166 5
255	Pepper Foot Cameraman	Method QPAM AQPAM CG-QPAM QPAM CG-QPAM QPAM AQPAM CG-QPAM QPAM AQPAM CG-QPAM	27.584 27.113 24.968 27.123 26.484 24.833 23.849 23.704 24.833 24.075 23.534	0.761 0.750 0.734 0.876 0.870 0.836 0.720 0.836 0.720 0.836 0.670 0.656	9.394 4.658 0.301 7.434 5.633 0.251 1.079 0.847 0.251 4.881 4.372	170 154 9 279 194 5 211 166 5 174 158 7
255	Pepper Foot Cameraman Pepper	Method QPAM AQPAM CG-QPAM AQPAM CG-QPAM QPAM AQPAM CG-QPAM QPAM AQPAM CG-QPAM	27.584 27.113 24.968 27.123 26.484 24.833 23.849 23.704 24.833 24.075 23.534 21.212	0.761 0.750 0.734 0.876 0.870 0.836 0.720 0.836 0.720 0.836 0.670 0.656 0.637	9.394 4.658 0.301 7.434 5.633 0.251 1.079 0.847 0.251 4.881 4.372 0.199	17(0 154 9 279 194 5 211 166 5 174 158 7 285
255	Pepper Foot Cameraman Pepper	Method QPAM AQPAM CG-QPAM QPAM CG-QPAM QPAM AQPAM CG-QPAM QPAM AQPAM CG-QPAM	27.584 27.113 24.968 27.123 26.484 24.833 23.849 23.704 24.833 24.075 23.534 21.212 23.815	0.761 0.750 0.734 0.876 0.870 0.836 0.720 0.836 0.670 0.636 0.637 0.865	9.394 4.658 0.301 7.434 5.633 0.251 1.079 0.847 0.251 4.881 4.372 0.199 7.738	170 154 9 279 194 5 211 166 5 174 158 7 285
255	Pepper Foot Cameraman Pepper Foot	Method QPAM AQPAM CG-QPAM AQPAM CG-QPAM AQPAM CG-QPAM AQPAM CG-QPAM AQPAM CG-QPAM AQPAM CG-QPAM	27.584 27.113 24.968 27.123 26.484 24.833 23.849 23.704 24.833 24.075 23.534 21.212 23.815 23.061 20.945	0.761 0.750 0.734 0.876 0.870 0.836 0.720 0.836 0.720 0.836 0.656 0.637 0.865 0.858 0.810	9.394 4.658 0.301 7.434 5.633 0.251 1.079 0.847 0.251 4.881 4.372 0.199 7.738 5.930 0.147	170 154 9 279 194 5 211 166 5 174 158 7 285 212 5
255	Pepper Foot Cameraman Pepper	Method QPAM AQPAM CG-QPAM QPAM CG-QPAM QPAM AQPAM CG-QPAM QPAM AQPAM CG-QPAM QPAM AQPAM	27.584 27.113 24.968 27.123 26.484 24.833 23.849 23.704 24.833 24.075 23.534 21.212 23.815 23.061	0.761 0.750 0.734 0.876 0.870 0.836 0.720 0.836 0.720 0.836 0.670 0.656 0.637 0.865 0.858	9.394 4.658 0.301 7.434 5.633 0.251 1.079 0.847 0.251 4.881 4.372 0.199 7.738 5.930	170 154 9 279 194 5 211 166 5 174 158 7 285 212

(b) Poisson Noise

TABLE I: Comparison of methods for Pepper, Foot, and Cameraman images with two different noise types.

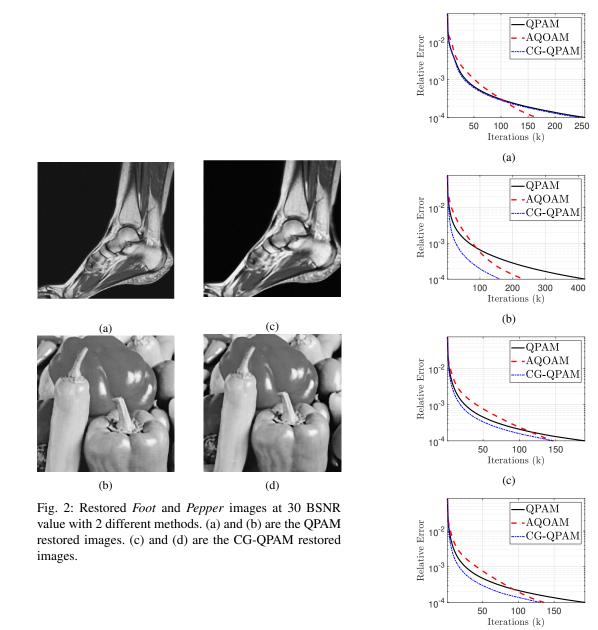


Fig. 3: (a) and (b) BSNR=20. (c) and (d) BSNR=30. The λ in (a) is 0.9 and (b) is 4.0. The λ in (c) is 5.2 and (d) is 7.0. The value of λ can improve the convergence of the CG-QPAM

(d)