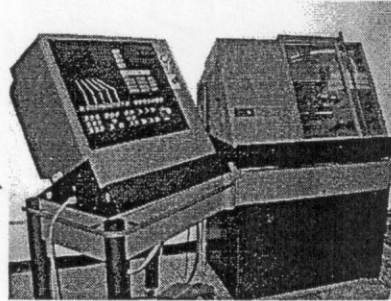


CNC Programming

Lecture 14, 15

Advanced Manufacturing



20 January 2009

Assoc Prof Zainal Abidin Ahmad

2

Overview

A numerical control, or "NC", system controls many machine functions and movements which were traditionally performed by skilled machinists.

Numerical control developed out of the need to meet the requirements of high production rates, uniformity and consistent part quality.

Programmed instructions are converted into output signals which in turn control machine operations such as spindle speeds, tool selection, tool movement, and cutting fluid flow.

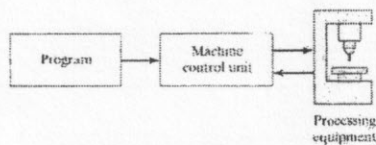


Figure 6.1 Basic components of an NC system.

20 January 2009

Assoc Prof Zainal Abidin Ahmad

3

Overview

By integrating a computer processor, computer numerical control, or "CNC" as it is now known, allows part machining programs to be edited and stored in the computer memory as well as permitting diagnostics and quality control functions during the actual machining.

All CNC machining begins with a part program, which is a sequential instructions or coded commands that direct the specific machine functions. The part program may be manually generated or, more commonly, generated by computer aided part programming systems.



Figure 1-8, Storm CNC lathe with hydraulic chucking and an electronically indexed 12 station turret. (Cincinnati Industrial, Inc.)

20 January 2009

Assoc Prof Zainal Abidin Ahmad

4

Basic CNC Principles

All computer controlled machines are able to accurately and repeatedly control motion in various directions. Each of these directions of motion is called an axis. Depending on the machine type there are commonly two to five axes.

Additionally, a CNC axis may be either a linear axis in which movement is in a straight line, or a rotary axis with motion following a circular path.

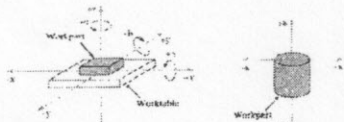


Figure 6.2 Coordinate systems used in NC: (a) for flat and prismatic work and (b) for rotational work. (On most turning machines, the Z-axis is horizontal rather than vertical as we have shown it.)

20 January 2009

5

Each axis consists of a mechanical component, such as a slide that moves, a servo drive motor that powers the mechanical movement, and a ball screw to transfer the power from the servo drive motor to the mechanical component. These components, along with the computer controls that govern them, are referred to as an axis drive system.

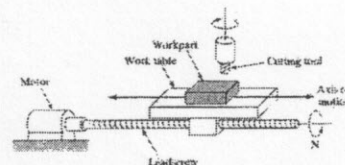


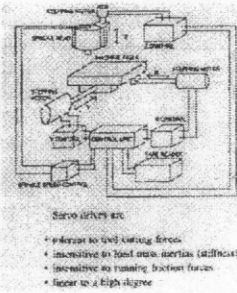
Figure 6.26 Motor and lead screw arrangement in an NC positioning system.

20 January 20

6

Basic CNC Principles

Using a vertical mill machining center as an example, there are typically three linear axes of motion. Each is given an alphabetic designation or address. The machine table motion side to side is called the "X" axis. Table movement in and out is the "Y" axis, while head movement up and down the column is the "Z" axis.



20 January 2009

Assoc Prof Zainal Abidin Ahmad

7

Basic CNC Principles

If a rotary table is added to the machine table, then the fourth axis is designated the "b" axis.

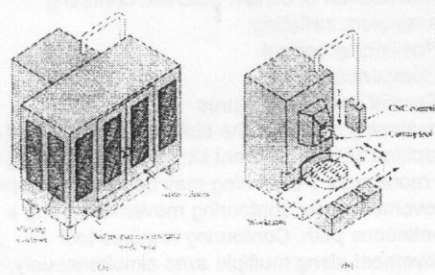


Figure 6.11 (a) four-axis CNC horizontal milling machine with safety fences installed and (b) with safety fences removed to show 15° axial axis reconfiguration for the horizontal specific.

20 January

8

Work Positioning

The method of accurate work positioning in relation to the cutting tool is called the "rectangular coordinate system." On the vertical mill, the horizontal base line is designated the "X" axis, while the vertical base line is designated the "Y" axis. The "Z" axis is at a right angle, perpendicular to both the "X" and "Y" axes.

Increments for all base lines are specified in linear measurements, for most machines the smallest increment is one ten-thousandth of an inch (.0001). If the machine is graduated in metric the smallest increment is usually one thousandth of a millimeter (.001mm).

The rectangular coordinate system allows the mathematical plotting of points in space. These points or locations are called "coordinates." The coordinates in turn relate to the tool center and dictate the "tool path" through the work.

20 January 2009

Assoc Prof Zainal Abidin Ahmad

9

Basic CNC Principles

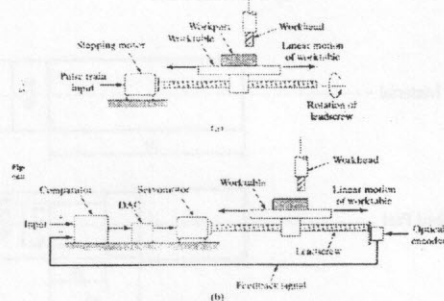


Figure 6.27 Two types of motion control in NC: (a) open loop and (b) closed loop.

20 January

10

CNC Programming Basics

CNC instructions are called part program commands.

When running, a part program is interpreted one command line at a time until all lines are completed.

Commands, which are also referred to as blocks, are made up of words which each begin with a letter address and end with a numerical value.

20 January 2009

Assoc Prof Zainal Abidin Ahmad

11

CNC Programming Basics

- Each letter address relates to a specific machine function. "G" and "M" letter addresses are two of the most common. A "G" letter specifies certain machine preparations such as inch or metric modes, or absolutes versus incremental modes.
- A "M" letter specifies miscellaneous machine functions and work like on/off switches for coolant flow, tool changing, or spindle rotation. Other letter addresses are used to direct a wide variety of other machine commands.

20 January 2009

Assoc Prof Zainal Abidin Ahmad

12

Program Command Parameters

Optimum machine programming requires consideration of certain machine operating parameters including:

- Positioning control
- Compensations
- Special machine features

Positioning control is the ability to program tool and machine slide movement simultaneously along two or more axes. Positioning may be for point-to-point movement or for contouring movement along a continuous path. Contouring requires tool movement along multiple axes simultaneously.

20 January 2009

Assoc Prof Zainal Abidin Ahmad

13

Program Command Parameters

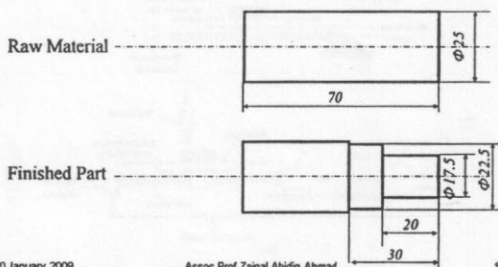
- Contouring requires tool movement along multiple axes simultaneously. This movement is referred to as "Interpolation" which is the process of calculating intermediate values between specific points along a programmed path and outputting those values as a precise motion.
- Interpolation may be linear having just a start and end point along a straight line, or circular which requires an end point, a center and a direction around the arc.

20 January 2009

Assoc Prof Zainal Abidin Ahmad

14

Programming Example Cylindrical Part



20 January 2009

Assoc Prof Zainal Abidin Ahmad

15

Programming Example Cylindrical Part

```

O0013
N0005 G53
N0010 T0303
N0020 G57 G00 X26.00 Z0.0 S500 M04
N0030 G01 X-0.20 F100
N0040 G00 Z2.0
N0050 X50.0 Z50.0
N0060 T0404
N0070 G57 G00 X22.50 Z2.0 S500
N0080 G01 Z-30.0 F100
N0090 G00 X23.0 Z2.0 S500
N0100 G84 X17.5 Z-20.0 D0=200 D2=200 D3=650
N0110 G00 Z2.0
N0120 X50.0 Z50.0
N0130 M30
    
```

20 January 2009

Assoc Prof Zainal Abidin Ahmad

16

Program Interpretation

O0013
Program identification number

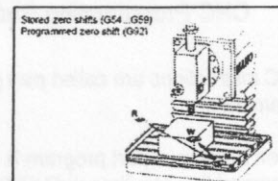
20 January 2009

Assoc Prof Zainal Abidin Ahmad

17

Program Interpretation

O0013
N0005 G53
To cancel any previous working zero point



R = Reference point (maximum travel of machine)
M = Machine zero point (0,0,0) of machine coordinate system.
W = Part zero point (workpiece coordinate system).

Under G54...G59 the actual machine coordinates of part zero are stored in the stored zero offset memory and activated in the part program.

Under G92 the actual machine coordinates are inserted and used on the G92 line of the part program.

Fig. 13 The relationship between the part zero and the machine system of coordinates. (Decker/Maho, Inc.)

20 January 2009

Program Interpretation

O0013
 N0005 G53
 N0010 T0303
 N0010 Sequence number
 T0303 Select tool number 303

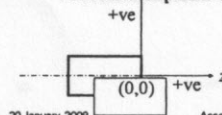
20 January 2009

Assoc Prof Zainal Abidin Ahmad

19

Program Interpretation

O0013
 N0005 G53
 N0010 T0404
 N0020 G57 G00 X26.0 Z0.0 S500 M04
 G57 To set the working zero point as saved
 G00 Rapid movement (no cutting)
 X26.0 X location (as a diameter; 13 form zero)
 Z0.0 Z location
 S500 Spindle speed is 500 rpm
 M04 Rotate spindle counterclockwise



20 January 2009

Assoc Prof Zainal Abidin Ahmad

20

Program Interpretation

O0013
 N0005 G53
 N0010 T0404
 N0020 G57 G00 X26.00 Z0.0 S500 M04
 N0030 G01 X-0.20 F100

G01 Linear interpolation (cutting)
 X-0.20 Move only in x direction until you pass
 the center by 0.1 mm (facing)
 F100 Set feed rate to 100 mm/min.



20 January 2009

Assoc Prof Zainal Abidin Ahmad

21

Program Interpretation

O0013
 N0005 G53
 N0010 T0404
 N0020 G57 G00 X26.00 Z0.0 S500 M04
 N0030 G01 X-0.20 F100
 N0040 G00 Z2.0

G00 Move rapidly away from workpiece (no cutting)
 Z2.0 the movement is 2 mm away from the face.

20 January 2009

Assoc Prof Zainal Abidin Ahmad

22

Program Interpretation

O0013
 N0005 G53
 N0010 T0404
 N0020 G57 G00 X26.00 Z0.0 S500 M04
 N0030 G01 X-0.20 F100
 N0040 G00 Z2.0
 N0050 X50.0 Z50.0

Go to a safe location away from the
 workpiece [x = 50 (25 from zero), z = 50] to
 change the tool.

20 January 2009

Assoc Prof Zainal Abidin Ahmad

23

Program Interpretation

O0013
 N0005 G53
 N0010 T0404
 N0020 G57 G00 X26.00 Z0.0 S500 M04
 N0030 G01 X-0.20 F100
 N0040 G00 Z2.0
 N0050 X50.0 Z50.0
 N0060 T0404

T0404 Select tool number 404

20 January 2009

Assoc Prof Zainal Abidin Ahmad

24

Program Interpretation

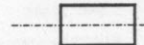
O0013
 N0005 G53
 N0010 T0404
 N0020 G57 G00 X26.00 Z0.0 S500 M04
 N0030 G01 X-0.20 F100
 N0040 G00 Z2.0
 N0050 X50.0 Z50.0
 N0060 T0404
 N0070 G57 G00 X22.50 Z2.0 S500
 G57 PS0
 G00 Rapid movement (no cutting)
 X22.50 X location (as a diameter; 11.25 form zero)
 Z2.0 Z location
 S500 Spindle speed is 500 rpm

20 January 2009 Assoc Prof Zainal Abidin Ahmad

25

Program Interpretation

O0013
 N0005 G53
 N0010 T0404
 N0020 G57 G00 X26.00 Z0.0 S500 M04
 N0030 G01 X-0.20 F100
 N0040 G00 Z2.0
 N0050 X50.0 Z50.0
 N0060 T0404
 N0070 G57 G00 X25.00 Z2.0 S500 M04
 N0080 G01 Z-30.0 F100
 G01 Linear interpolation (cutting)
 Z-30 Move only in z direction (external turning)
 F100 Set feed rate to 100 mm/min.



20 January 2009 Assoc Prof Zainal Abidin Ahmad

26

Program Interpretation

O0013
 N0005 G53
 N0010 T0404
 N0020 G57 G00 X26.00 Z0.0 S500 M04
 N0030 G01 X-0.20 F100
 N0040 G00 Z2.0
 N0050 X50.0 Z50.0
 N0060 T0404
 N0070 G57 G00 X25.00 Z2.0 S500 M04
 N0080 G01 X22.5 Z-70.0 F100
 N0090 G00 X23.0 Z2.0 S500
 G00 Move rapidly away from workpiece (no cutting) to location x = 23.0 (11.50 from zero) and z = 2.0.

20 January 2009 Assoc Prof Zainal Abidin Ahmad

27

Program Interpretation

O0013
 N0005 G53
 N0010 T0404
 N0020 G57 G00 X26.00 Z0.0 S500 M04
 N0030 G01 X-0.20 F100
 N0040 G00 Z2.0
 N0050 X50.0 Z50.0
 N0060 T0404
 N0070 G57 G00 X25.00 Z2.0 S500 M04
 N0080 G01 X22.5 Z-70.0 F100
 N0090 G00 X26.0 Z2.0 S500
 N0100 G84 X17.5 Z-20.0 D0=200 D2=200 D3=650
 G84 Turning cycle for machining the step
 X17.5 final diameter
 Z-20 length of step is 20 mm
 D0=200 Finish allowance in X direction (0.2 mm)
 D2=200 Finish allowance in Z direction (0.2 mm)
 D3=650 Depth of cut in each pass (0.65 mm)



20 January 2009 Assoc Prof Zainal Abidin Ahmad

28

Program Interpretation

O0013
 N0005 G53
 N0010 T0404
 N0020 G57 G00 X26.00 Z0.0 S500 M04
 N0030 G01 X-0.20 F100
 N0040 G00 Z2.0
 N0050 X50.0 Z50.0
 N0060 T0404
 N0070 G57 G00 X25.00 Z2.0 S500 M04
 N0080 G01 X22.5 Z-70.0 F100
 N0090 G00 X26.0 Z2.0 S500
 N0100 G84 X17.5 Z-20.0 D0=200 D2=200 D3=650
 N0110 G00 Z2.0
 G00 Move rapidly away from workpiece (no cutting)
 Z2.0 the movement is 2 mm away from the face.

20 January 2009 Assoc Prof Zainal Abidin Ahmad

29

Program Interpretation

O0013
 N0005 G53
 N0010 T0404
 N0020 G57 G00 X26.00 Z0.0 S500 M04
 N0030 G01 X-0.20 F100
 N0040 G00 Z2.0
 N0050 X50.0 Z50.0
 N0060 T0404
 N0070 G57 G00 X25.00 Z2.0 S500 M04
 N0080 G01 X22.5 Z-70.0 F100
 N0090 G00 X26.0 Z2.0 S500
 N0100 G84 X17.5 Z-20.0 D0=200 D2=200 D3=650
 N0110 G00 Z2.0
 N0120 X50.0 Z50.0
 X50.0 Z50.0 Move to the tool changing location

20 January 2009 Assoc Prof Zainal Abidin Ahmad

30

Program Interpretation

```

O0013
N0005 G53
N0010 T0404
N0020 G57 G00 X26.00 Z0.0 S500 M04
N0030 G01 X-0.20 F100
N0040 G00 Z2.0
N0050 X50.0 Z50.0
N0060 T0404
N0070 G57 G00 X25.00 Z2.0 S500 M04
N0080 G01 X22.5 Z-70.0 F100
N0090 G00 X26.0 Z2.0 S500
N0100 G84 X17.5 Z-20.0 D1=200 D2=200 D3=650
N0110 G00 Z2.0
N0120 X50.0 Z50.0 T00
N0130 M30
    
```

M30 Program End

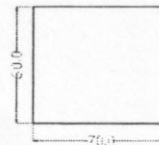
20 January 2009

Assoc Prof Zainal Abidin Ahmad

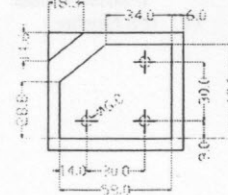
31

Programming Example

Raw Material



Finished Part

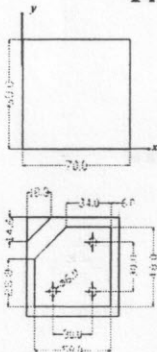


20 January 2009

Assoc Prof Zainal Abidin Ahmad

32

Programming Example



```

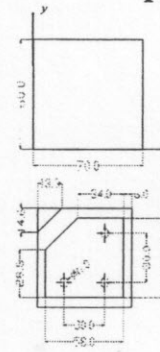
G55 X200 Y80
Program 1
N001 M06 T1
N002 M03 rpm 400
N003 G01 X-8 Y0 Z0 XYFeed 150
N004 G01 X-8 Y0 Z-0.5 ZFeed 150
N005 G01 X70 Y0 Z-0.5 XYFeed 75
N006 G01 X70 Y60 Z-0.5 XYFeed 75
N007 G01 X30 Y60 Z-0.5 XYFeed 75
N008 G01 X0 Y40 Z-0.5 XYFeed 75
N009 G01 X0 Y0 Z-0.5 XYFeed 75
N010 G81 R3 E9 N7 Z-0.5
N011 M05
N012 M02
    
```

20 January 2009

Assoc Prof Zainal Abidin Ahmad

33

Programming Example



```

Tool Change
G55 X200 Y80
Program 2
N001 M06 T2
N002 M03 rpm 400
N003 G01 X-8 Y0 Z0 XYFeed 150
N004 G01 X20 Y15 Z10 XYFeed 150 ZFeed 150
N005 G01 X20 Y15 Z-10 ZFeed 75
N006 G01 X20 Y15 Z10 ZFeed 150
N007 G01 X50 Y15 Z10 ZFeed 150
N008 G01 X50 Y15 Z-10 ZFeed 75
N009 G01 X50 Y15 Z10 ZFeed 150
N010 G01 X50 Y45 Z10 ZFeed 150
N011 G01 X50 Y45 Z-10 ZFeed 75
N012 G01 X50 Y45 Z10 ZFeed 150
N013 M05
N014 M02
    
```

20 January 2009

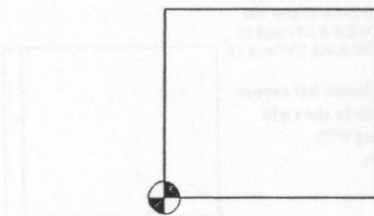
Assoc Prof Zainal Abidin Ahmad

34

Program Interpretation

G55 X200 Y80

Setting the datum to the lower left corner of the work piece



20 January 2009

Assoc Prof Zainal Abidin Ahmad

35

Program Interpretation

G55 X200 Y80

Program 1

Program Identification Number



20 January 2009

Assoc Prof Zainal Abidin Ahmad

36

Program Interpretation

G55 X200 Y80
 Program 1
 N001 M06 T1

 N001 Sequence Number
 M06 Tool Change (End Mill with
 Diameter=12mm
 T1 Tool Number

20 January 2009 Assoc Prof Zainal Abidin Ahmad 37

Program Interpretation

G55 X200 Y80
 Program 1
 N001 M06 T1
 N002 M03 rpm 400

 Start rotating the spindle clockwise with 400
 rpm

20 January 2009 Assoc Prof Zainal Abidin Ahmad 38

Program Interpretation

G55 X200 Y80
 Program 1
 N001 M06 T1
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150

 Go to Safe Position with feed 150mm/min

20 January 2009 Assoc Prof Zainal Abidin Ahmad 39

Program Interpretation

G55 X200 Y80
 Program 1
 N001 M06 T1
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X-8 Y0 Z-0.5 ZFeed 150

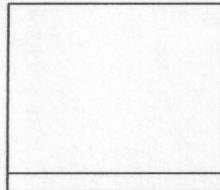
 Lower the end mill to determine the depth of
 cut

20 January 2009 Assoc Prof Zainal Abidin Ahmad 40

Program Interpretation

G55 X200 Y80
 Program 1
 N001 M06 T1
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X-8 Y0 Z-0.5 ZFeed 150
 N005 G01 X70 Y0 Z-0.5 XYFeed 75

Move from the lower left corner
 of the work piece to the right
 lower one cutting with
 feed=75mm/min

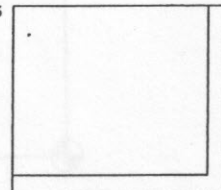


20 January 2009 Assoc Prof Zainal Abidin Ahmad 41

Program Interpretation

G55 X200 Y80
 Program 1
 N001 M06 T1
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X-8 Y0 Z-0.5 ZFeed 150
 N005 G01 X70 Y0 Z-0.5 XYFeed 75
 N006 G01 X70 Y60 Z-0.5 XYFeed 75

Move from the lower left corner
 of the work piece to the right
 lower one cutting with
 feed=75mm/min

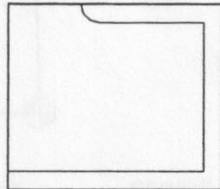


20 January 2009 Assoc Prof Zainal Abidin Ahmad 42

Program Interpretation

```
G55 X200 Y80
Program 1
N001 M06 T1
N002 M03 rpm 400
N003 G01 X-8 Y0 Z0 XYFeed 150
N004 G01 X-8 Y0 Z-0.5 ZFeed 150
N005 G01 X70 Y0 Z-0.5 XYFeed 75
N006 G01 X70 Y60 Z-0.5 XYFeed 75
N007 G01 X30 Y60 Z-0.5 XYFeed 75
```

Cutting the horizontally up to X=30



20 January 2009

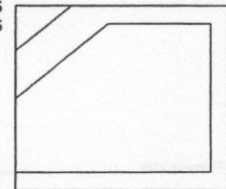
Assoc Prof Zainal Abidin Ahmad

43

Program Interpretation

```
G55 X200 Y80
Program 1
N001 M06 T1
N002 M03 rpm 400
N003 G01 X-8 Y0 Z0 XYFeed 150
N004 G01 X-8 Y0 Z-0.5 ZFeed 150
N005 G01 X70 Y0 Z-0.5 XYFeed 75
N006 G01 X70 Y60 Z-0.5 XYFeed 75
N007 G01 X30 Y60 Z-0.5 XYFeed 75
N008 G01 X0 Y40 Z-0.5 XYFeed 75
```

Cutting to X=0 & Y=40



20 January 2009

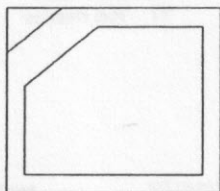
Assoc Prof Zainal Abidin Ahmad

44

Program Interpretation

```
G55 X200 Y80
Program 1
N001 M06 T1
N002 M03 rpm 400
N003 G01 X-8 Y0 Z0 XYFeed 150
N004 G01 X-8 Y0 Z-0.5 ZFeed 150
N005 G01 X70 Y0 Z-0.5 XYFeed 75
N006 G01 X70 Y60 Z-0.5 XYFeed 75
N007 G01 X30 Y60 Z-0.5 XYFeed 75
N008 G01 X0 Y40 Z-0.5 XYFeed 75
N009 G01 X0 Y0 Z-0.5 XYFeed 75
```

Complete the countering



20 January 2009

Assoc Prof Zainal Abidin Ahmad

45

Program Interpretation

```
G55 X200 Y80
Program 1
N001 M06 T1
N002 M03 rpm 400
N003 G01 X-8 Y0 Z0 XYFeed 150
N004 G01 X-8 Y0 Z-0.5 ZFeed 150
N005 G01 X70 Y0 Z-0.5 XYFeed 75
N006 G01 X70 Y60 Z-0.5 XYFeed 75
N007 G01 X30 Y60 Z-0.5 XYFeed 75
N008 G01 X0 Y40 Z-0.5 XYFeed 75
N009 G01 X0 Y0 Z-0.5 XYFeed 75
N010 G81 R3 E9 N7 Z-0.5
```

Repeat 7 times blocks from N003 to N009 with incremental offset of Z=-0.5

Handwritten note: "Canting hot thing... Sim... illustration of the idea"

20 January 2009

Assoc Prof Zainal Abidin Ahmad

46

Program Interpretation

```
G55 X200 Y80
Program 1
N001 M06 T1
N002 M03 rpm 400
N003 G01 X-8 Y0 Z0 XYFeed 150
N004 G01 X-8 Y0 Z-0.5 ZFeed 150
N005 G01 X70 Y0 Z-0.5 XYFeed 75
N006 G01 X70 Y60 Z-0.5 XYFeed 75
N007 G01 X30 Y60 Z-0.5 XYFeed 75
N008 G01 X0 Y40 Z-0.5 XYFeed 75
N009 G01 X0 Y0 Z-0.5 XYFeed 75
N010 G81 R3 E9 N7 Z-0.5
N011 M05
```

Spindle Off

20 January 2009

Assoc Prof Zainal Abidin Ahmad

47

Program Interpretation

```
G55 X200 Y80
Program 1
N001 M06 T1
N002 M03 rpm 400
N003 G01 X-8 Y0 Z0 XYFeed 150
N004 G01 X-8 Y0 Z-0.5 ZFeed 150
N005 G01 X70 Y0 Z-0.5 XYFeed 75
N006 G01 X70 Y60 Z-0.5 XYFeed 75
N007 G01 X30 Y60 Z-0.5 XYFeed 75
N008 G01 X0 Y40 Z-0.5 XYFeed 75
N009 G01 X0 Y0 Z-0.5 XYFeed 75
N010 G81 R3 E9 N7 Z-0.5
N011 M05
N012 M02
```

End Program

20 January 2009

Assoc Prof Zainal Abidin Ahmad

48

Program Interpretation

Tool Change

Changing the tool



20 January 2009

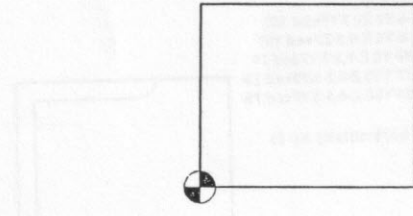
Assoc Prof Zainal Abidin Ahmad

49

Program Interpretation

Tool Change
G55 X200 Y80

Setting the datum to the lower left corner of the work piece



20 January 2009

Assoc Prof Zainal Abidin Ahmad

50

Program Interpretation

Tool Change
G55 X200 Y80
Program 2

Program Identification Number

20 January 2009

Assoc Prof Zainal Abidin Ahmad

51

Program Interpretation

Tool Change
G55 X200 Y80
Program 2
N001 M06 T2

N001 Sequence Number
M06 Tool Change (Drill with
Diameter=6mm
T2 Tool Number

20 January 2009

Assoc Prof Zainal Abidin Ahmad

52

Program Interpretation

Tool Change
G55 X200 Y80
Program 2
N001 M06 T2
N002 M03 rpm 400

Start rotating the spindle clockwise with 400 rpm

20 January 2009

Assoc Prof Zainal Abidin Ahmad

53

Program Interpretation

Tool Change
G55 X200 Y80
Program 2
N001 M06 T2
N002 M03 rpm 400
N003 G01 X-8 Y0 Z0 XYFeed 150

Go to Safe Position with feed 150mm/min

20 January 2009

Assoc Prof Zainal Abidin Ahmad

54

Program Interpretation

Tool Change
 G55 X200 Y80
 Program 2
 N001 M06 T2
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X20 Y15 Z10 XYFeed 150 ZFeed 150

Stop above the center of the first hole

20 January 2009

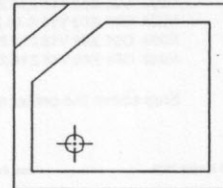
Assoc Prof Zainal Abidin Ahmad

55

Program Interpretation

Tool Change
 G55 X200 Y80
 Program 2
 N001 M06 T2
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X20 Y15 Z10 XYFeed 150 ZFeed 150
 N005 G01 X20 Y15 Z-10 ZFeed 75

Start Drill the first hole



20 January 2009

Assoc Prof Zainal Abidin Ahmad

56

Program Interpretation

Tool Change
 G55 X200 Y80
 Program 2
 N001 M06 T2
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X20 Y15 Z10 XYFeed 150 ZFeed 150
 N005 G01 X20 Y15 Z-10 ZFeed 75
 N006 G01 X20 Y15 Z10 ZFeed 150

Retract to a position above the hole

20 January 2009

Assoc Prof Zainal Abidin Ahmad

57

Program Interpretation

Tool Change
 G55 X200 Y80
 Program 2
 N001 M06 T2
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X20 Y15 Z10 XYFeed 150 ZFeed 150
 N005 G01 X20 Y15 Z-10 ZFeed 75
 N006 G01 X20 Y15 Z10 ZFeed 150
 N007 G01 X50 Y15 Z10 ZFeed 150

Stop above the center of the second hole

20 January 2009

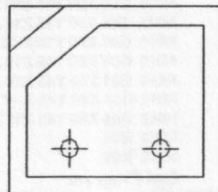
Assoc Prof Zainal Abidin Ahmad

58

Program Interpretation

Tool Change
 G55 X200 Y80
 Program 2
 N001 M06 T2
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X20 Y15 Z10 XYFeed 150 ZFeed 150
 N005 G01 X20 Y15 Z-10 ZFeed 75
 N006 G01 X20 Y15 Z10 ZFeed 150
 N007 G01 X50 Y15 Z10 ZFeed 150
 N008 G01 X50 Y15 Z-10 ZFeed 75

Drill the second hole



20 January 2009

Assoc Prof Zainal Abidin Ahmad

59

Program Interpretation

Tool Change
 G55 X200 Y80
 Program 2
 N001 M06 T2
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X20 Y15 Z10 XYFeed 150 ZFeed 150
 N005 G01 X20 Y15 Z-10 ZFeed 75
 N006 G01 X20 Y15 Z10 ZFeed 150
 N007 G01 X50 Y15 Z10 ZFeed 150
 N008 G01 X50 Y15 Z-10 ZFeed 75
 N009 G01 X50 Y15 Z10 ZFeed 150

Retract to a position above the second hole

20 January 2009

Assoc Prof Zainal Abidin Ahmad

60

Program Interpretation

Tool Change
 G55 X200 Y80
 Program 2
 N001 M06 T2
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X20 Y15 Z10 XYFeed 150 ZFeed 150
 N005 G01 X20 Y15 Z-10 ZFeed 75
 N006 G01 X20 Y15 Z10 ZFeed 150
 N007 G01 X50 Y15 Z10 ZFeed 150
 N008 G01 X50 Y15 Z-10 ZFeed 75
 N009 G01 X50 Y15 Z10 ZFeed 150
 N010 G01 X50 Y45 Z10 ZFeed 150

Stop above the center of the third hole

20 January 2009

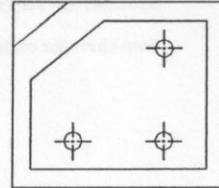
Assoc Prof Zainal Abidin Ahmad

61

Program Interpretation

Tool Change
 G55 X200 Y80
 Program 2
 N001 M06 T2
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X20 Y15 Z10 XYFeed 150 ZFeed 150
 N005 G01 X20 Y15 Z-10 ZFeed 75
 N006 G01 X20 Y15 Z10 ZFeed 150
 N007 G01 X50 Y15 Z10 ZFeed 150
 N008 G01 X50 Y15 Z-10 ZFeed 75
 N009 G01 X50 Y15 Z10 ZFeed 150
 N010 G01 X50 Y45 Z10 ZFeed 150
 N011 G01 X50 Y45 Z-10 ZFeed 75

Drill the third hole



20 January 2009

Assoc Prof Zainal Abidin Ahmad

62

Program Interpretation

Tool Change
 G55 X200 Y80
 Program 2
 N001 M06 T2
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X20 Y15 Z10 XYFeed 150 ZFeed 150
 N005 G01 X20 Y15 Z-10 ZFeed 75
 N006 G01 X20 Y15 Z10 ZFeed 150
 N007 G01 X50 Y15 Z10 ZFeed 150
 N008 G01 X50 Y15 Z-10 ZFeed 75
 N009 G01 X50 Y15 Z10 ZFeed 150
 N010 G01 X50 Y45 Z10 ZFeed 150
 N011 G01 X50 Y45 Z-10 ZFeed 75
 N012 G01 X50 Y45 Z10 ZFeed 150

Retract to a position above the third hole

20 January 2009

Assoc Prof Zainal Abidin Ahmad

63

Program Interpretation

Tool Change
 G55 X200 Y80
 Program 2
 N001 M06 T2
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X20 Y15 Z10 XYFeed 150 ZFeed 150
 N005 G01 X20 Y15 Z-10 ZFeed 75
 N006 G01 X20 Y15 Z10 ZFeed 150
 N007 G01 X50 Y15 Z10 ZFeed 150
 N008 G01 X50 Y15 Z-10 ZFeed 75
 N009 G01 X50 Y15 Z10 ZFeed 150
 N010 G01 X50 Y45 Z10 ZFeed 150
 N011 G01 X50 Y45 Z-10 ZFeed 75
 N012 G01 X50 Y45 Z10 ZFeed 150
 N013 M05

Spindle off

20 January 2009

Assoc Prof Zainal Abidin Ahmad

64

Program Interpretation

Tool Change
 G55 X200 Y80
 Program 2
 N001 M06 T2
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X20 Y15 Z10 XYFeed 150 ZFeed 150
 N005 G01 X20 Y15 Z-10 ZFeed 75
 N006 G01 X20 Y15 Z10 ZFeed 150
 N007 G01 X50 Y15 Z10 ZFeed 150
 N008 G01 X50 Y15 Z-10 ZFeed 75
 N009 G01 X50 Y15 Z10 ZFeed 150
 N010 G01 X50 Y45 Z10 ZFeed 150
 N011 G01 X50 Y45 Z-10 ZFeed 75
 N012 G01 X50 Y45 Z10 ZFeed 150
 N013 M05
 N014 M02
 End Program

20 January 2009

Assoc Prof Zainal Abidin Ahmad

65

Program Interpretation

Tool Change
 G55 X200 Y80
 Program 2
 N001 M06 T2
 N002 M03 rpm 400
 N003 G01 X-8 Y0 Z0 XYFeed 150
 N004 G01 X20 Y15 Z10 XYFeed 150 ZFeed 150
 N005 G01 X20 Y15 Z-10 ZFeed 75
 N006 G01 X20 Y15 Z10 ZFeed 150
 N007 G01 X50 Y15 Z10 ZFeed 150
 N008 G01 X50 Y15 Z-10 ZFeed 75
 N009 G01 X50 Y15 Z10 ZFeed 150
 N010 G01 X50 Y45 Z10 ZFeed 150
 N011 G01 X50 Y45 Z-10 ZFeed 75
 N012 G01 X50 Y45 Z10 ZFeed 150
 N013 M05
 N014 M02
 End Program

20 January 2009

Assoc Prof Zainal Abidin Ahmad

66